

MC1322x Simple Media Access Controller Demonstration Applications

User's Guide

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About This Book

This guide provides a detailed description of the MC1322x Simple Media Access Controller (MC1322x SMAC) demonstration applications. The demonstration applications are delivered as ANSI C source code and are included in the MC1322x SMAC Codebase. The Codebase is incorporated into the Freescale BeeKit Wireless Connectivity Toolkit. See the *BeeKit Wireless Connectivity Toolkit User's Guide* (BKWCTKUG) and the BeeKit on-line help for more information.

This guide explains how to run various MC1322x SMAC demonstration applications and provides information that allows users to more easily take advantage of these demonstration applications or modify the applications to fit their specific needs.

The demonstration applications shown in this guide are compatible with previous SMAC demonstrations at the protocol level. However, the applications that employ security will be different because the MC1322x SMAC takes advantage of the Advanced Security Module (ASM, AES based) security module included in the MC122x Platform in a Package (PiP). The MC1322x device provides a more robust security approach. For more information about security and the MC1322x, see the appropriate MC1322x documentation available at www.freescale.com/zigbee.

The MC1322x SMAC API is similar to previous SMAC APIs. For more detail about the APIs, see the *MC1322x Simple Media Access Controller (SMAC) Reference Manual* (22xSMACRM).

Available Devices

The MC1322x family is available as two part numbers. These device types differ only in their ROM contents, all other device hardware, performance, and specifications are identical:

- MC13224V - this is the original version and is the generic part type.
 - The MC13224V is intended for most IEEE 802.15.4 applications including MAC-based, ZigBee-2007 Profile 1, and ZigBee RF4CE targets.
 - It has a more complete set of peripheral drivers in ROM.
- MC13226V - this is a more recent version and is provided specifically for ZigBee-2007 Profile 2 (Pro) applications. Only the onboard ROM image has been changed to optimize ROM usage for the ZigBee Pro profile and maximize the amount of available RAM for application use.
 - The IEEE MAC/PHY functionality has been streamlined to include only that functionality required by the ZigBee specification. The MAC functionality is 802.15.4 compatible.
 - For a typical application, up to 20 kbytes more of RAM is available versus the M13224V
 - Some drivers present in the MC13224 ROM have been removed and these include the ADC, LCDfont, and SSI drivers. These drivers are still available as library functions, but now compile into the RAM space.
 - The Low Level Component (LLC) functionality has also been streamlined for the ZigBee specification

NOTE

- When running the Freescale IEEE 802.15.4 MAC (or a related stack) on the MC1322x platform, neither beaconing or GTS are supported.

- See the MC1322x Reference Manual (Document No MC1322xRM), for information on using applications on these devices.

Audience

This document is intended for application developers generating MC1322x SMAC demonstration applications from the Freescale BeeKit Wireless Connectivity Toolkit or modifying these applications as a starting point for proprietary applications.

Organization

This document is organized into ten chapters.

Chapter 1	Introduction — This chapter shows how to generate an SMAC demonstration application using BeeKit.
Chapter 2	Wireless UART — Provides a detailed description of MC1322x SMAC Wireless UART demonstration application.
Chapter 3	Connectivity Test — Provides an easy way to test the RF performance of the transceiver for basic transmitter and receiver tests. It includes test mode (continuous tx, modulated, unmodulated, etc.); Packet Error Rate and Range (LQI measurements).
Chapter 4	Accelerometer Test — Provides an overview of the Accelerometer Demonstration application, which shows various uses for the Freescale X, Y, and Z axes accelerometers.
Chapter 5	Low Power Bell — Shows how to implement different low power options.
Chapter 6	Generic Application — Provides a start template for users what want to add their own application.
Chapter 7	Simple ZTC — Allows users to test the SMAC primitives by sending special data frames through the Serial/USB port.
Chapter 8	Repeater — Implements a simple repeater which extends the range between two boards running an SMAC application demonstration.
Chapter 9	Weather Station — Simulates a Weather Station and shows the use of Freescale sensors for acceleration and pressure.
Chapter 10	Over The Air Programmer (OTAP) — Allows users to update a board's FLASH remotely without a physical connection. Given an OTAP enabled application and an OTAP programmer, users can replace an existing application with a new application.

Revision History

The following table summarizes revisions to this document since the previous release (Rev. 1.2).

Revision History

Location	Revision
Chapters 3 and 6	Various software updates.

Definitions, Acronyms, and Abbreviations

The following list defines the acronyms and abbreviations used in this document.

AES	Advanced Encryption Standard
API	Application Program Interface
ASM	Advanced Security Module
BDM	Background Debug Module
BDM debugger	A debugger using the BDM interface for communication with the MCU. An example is the P&E BDM Multilink debugger for HCS08.
CBC	Cipher Block Chaining.
CBC-MAC	Cipher Block Chaining Message Authentication Code.
CCM	Counter with CBC-MAC
CTR	Counter.
dBm	Decibels referred to one milliwatt.
ED	Energy Detect.
EN	End Node - Evaluation Board.
EVB	Evaluation Boards.
EVK	Evaluation Kit
EWB	Embedded Workbench IDE work space file
GUI	Graphical User Interface
IDE	Integrated Development Environment
LP	Low Power
MAC	Media Access Control
MAC	Message Authentication Code
MCU	MicroController Unit
NCB	Network Coordinator Board
NVM	None-Volatile Memory
OTAP	Over The Air Programming
PC	Personal Computer
PCB	Printed Circuit Board

PiP	Platform in Package
RX	Reception
S19	S - Record. 'S19' is the file extension used for the Freescale binary image format. The S19 file encapsulates the binary image as a list of ASCII records. Each record contains a length -, address -, data - and checksum field. The 16 bit address field allows a memory space for up to 64 KB. The S19 can be generated with CodeWarrior IDE and is the product from the linking process. S19 does not contain additional information to a debugger (where to look for source files).
Safe Mode Boot	The Embedded Bootloader boots up using safe default system values.
SMAC	Simple Media Access Control.
SN	Sensor Node Evaluation Board.
TX	Transmission.

References

The following sources were referenced to produce this book:

[1] Freescale 802.15.4 MAC/PHY Software Reference Manual (802154MPSRM)

[2] Freescale MC1322x Simple Media Access Controller (SMAC) Reference Manual (22xSMACRM)

Chapter 1

Generating an SMAC Application and Port Configuration

This chapter provides an overview of how to generate an SMAC demonstration application using BeeKit. This chapter only provides an overview of how to generate an SMAC demonstration application. For more details on installing BeeKit and BeeKit operation, see the *BeeKit Wireless Connectivity Toolkit User's Guide* (BKWCTKUG).

This chapter also shows how to set up a virtual UART/USB COM port. Once the ports are configured, refer to the appropriate application chapter in this guide.

1. Install and then launch BeeKit and the BeeKit main window appears as shown in [Figure 1-1](#).

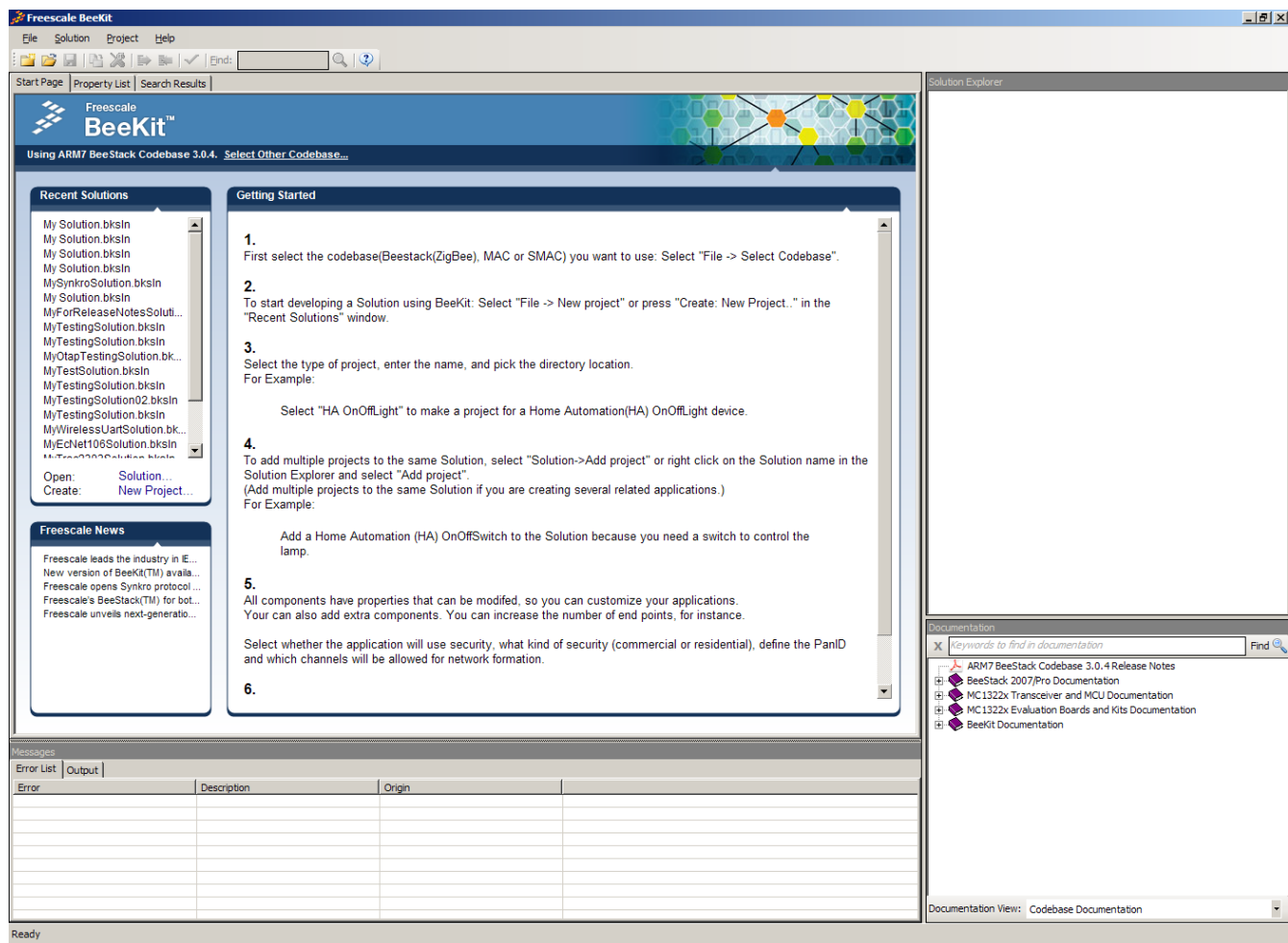


Figure 1-1. BeeKit Graphical User Interface

2. Select the SMAC Codebase as shown in [Figure 1-2](#).

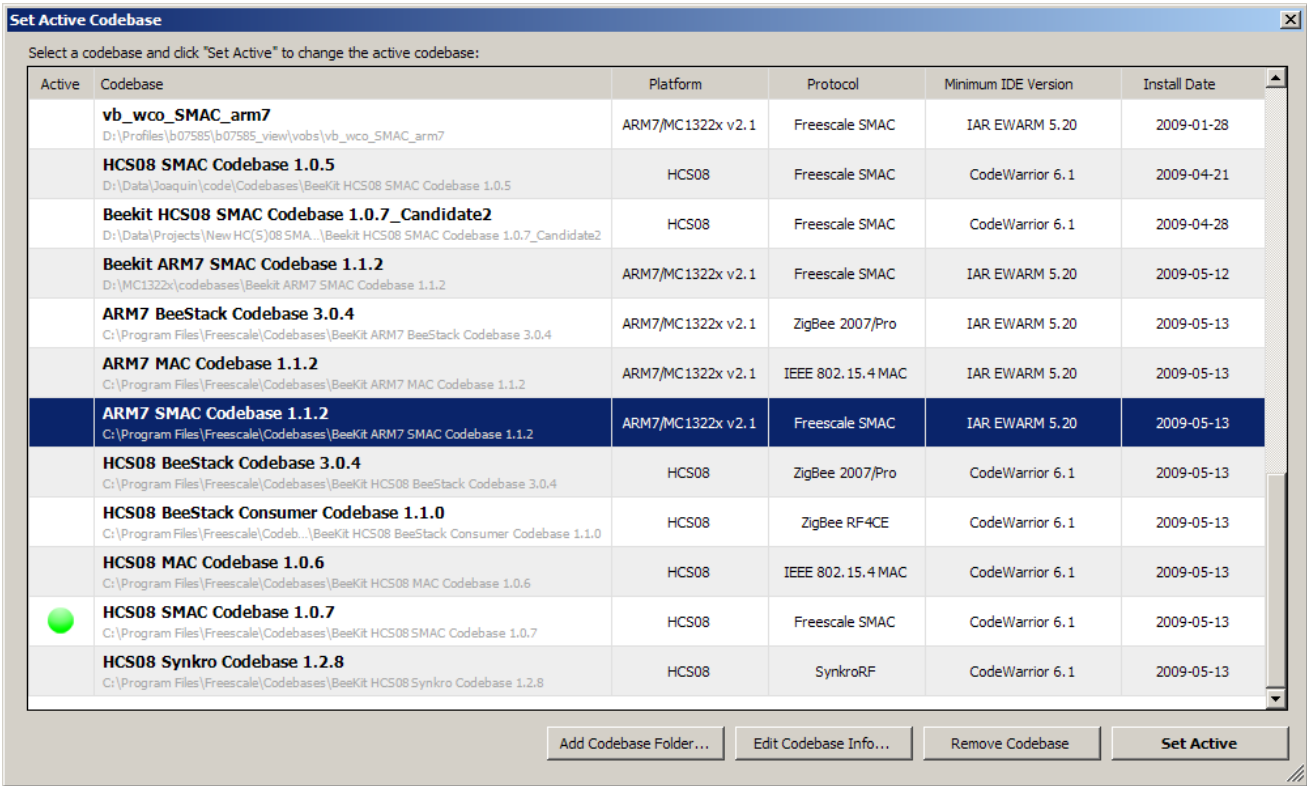


Figure 1-2. selecting SMAC Codebase

In BeeKit, a Codebase is a set of files and rules that permit users to generate the final applications. This step is important, because the SMAC Codebase is different than the Codebase of MAC and BeeStack.

3. Create a new project as shown in [Figure 1-3](#).

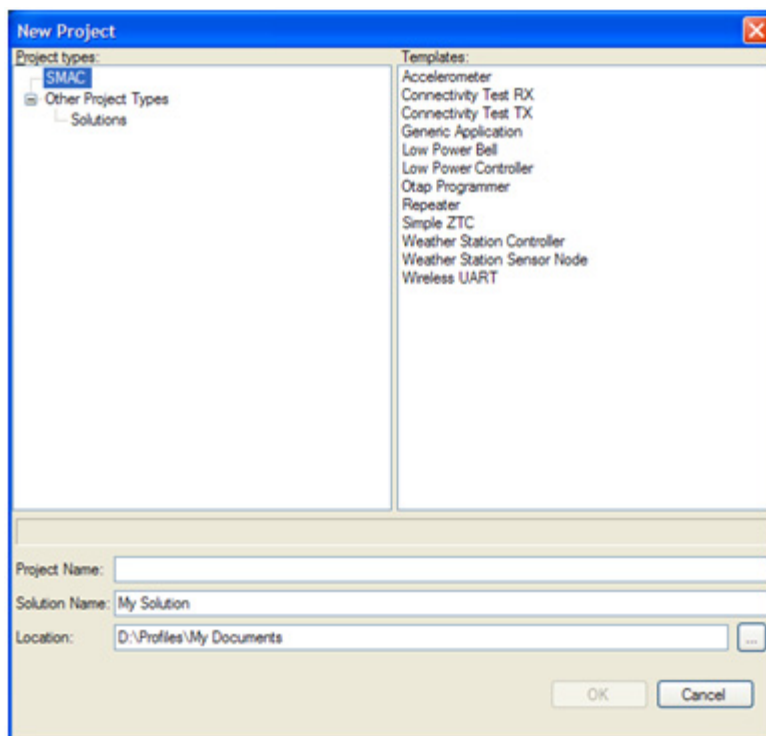


Figure 1-3. Creating a new project

If users create a new project and there is not a an existing solution, then users are also creating a solution. The solution must have a name. Specify a name for the solution.

4. Add other required projects for the evaluation as shown in [Figure 1-4](#).

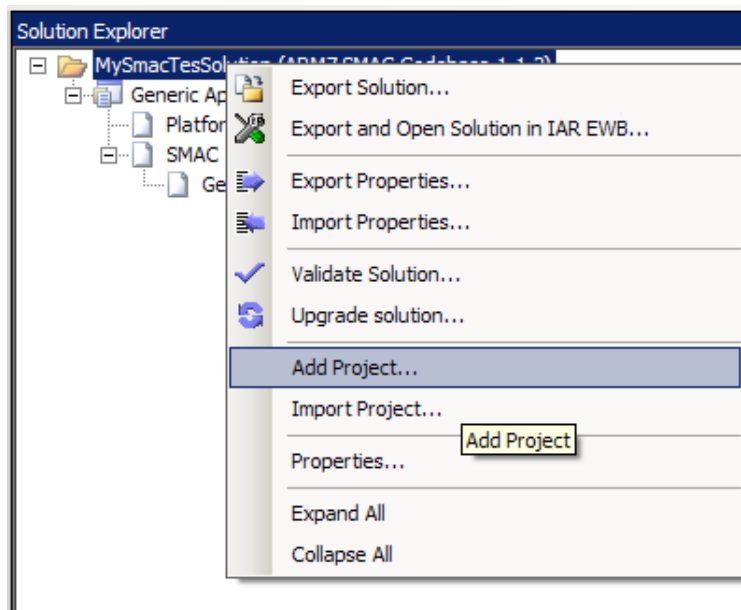


Figure 1-4. Adding a New Project to a Existing Solution

5. Modify the project properties as shown in [Table 1-1](#).

Table 1-1. Software Component Properties

Component	Property	Description
SMAC	Security Enabled	Enables the security Module to automatically encrypt the information sent and received.
	Promiscuous Mode	If set to true, the SMAC Code Bytes are not sent prior to the message.
	Security Type	This is the security engine used if the security enabled property is true.
	Security Default KEY0	Less Significant 32 bit Word of the 128 bits to be used as key on the ciphering engine.
	Security Default KEY1	Second Significant 32 bit Word of the 128 bits to be used as key on the ciphering engine.
	Security Default KEY2	Third Significant 32 bit Word of the 128 bits to be used as key on the ciphering engine.
	Security Default KEY3	More Significant 32 bit Word of the 128 bits to be used as key on the ciphering engine.
	Security Default COUNTER0	Less Significant 32 bit Word of the 128 bits to be used as initial counter on the ciphering engine.
	Security Default COUNTER1	Second Significant 32 bit Word of the 128 bits to be used as initial counter on the ciphering engine.
	Security Default COUNTER2	Third Significant 32 bit Word of the 128 bits to be used as initial counter on the ciphering engine.
	Security Default COUNTER3	More Significant 32 bit Word of the 128 bits to be used as initial counter on the ciphering engine.
PLM	Target hardware	Allows board selection.
	LCD Enabled	Includes support for LCDs.
	Default SCI Port	Selects the SCI port. Freescale ZigBee boards usually have SCI Port 1 connected to a DB9 connector and SCI port 2 connected to a USB connector.
	MCU Version	Can select either MC13224 or MC13226.
App	Default Channel	Default starting channel in the application.
	Output Power	Initial power output configuration.
	Baud Rate	Baud rate to be set at the default SCI port for this application
	OTAP Enabled	Enables the OTAP Module to allow over the air programming of the application.
	OTAP Request Code	If the OTAP Module is enabled the application will switch to OTAP mode when this OTAP Request Code is received.
	OTAP Device Id	This ID distinguishes between different devices identified by an OTAP Programmer.

6. Users must now validate the solution as shown in [Figure 1-5](#). The validation process helps users find possible inconsistencies between the selected hardware and properties.

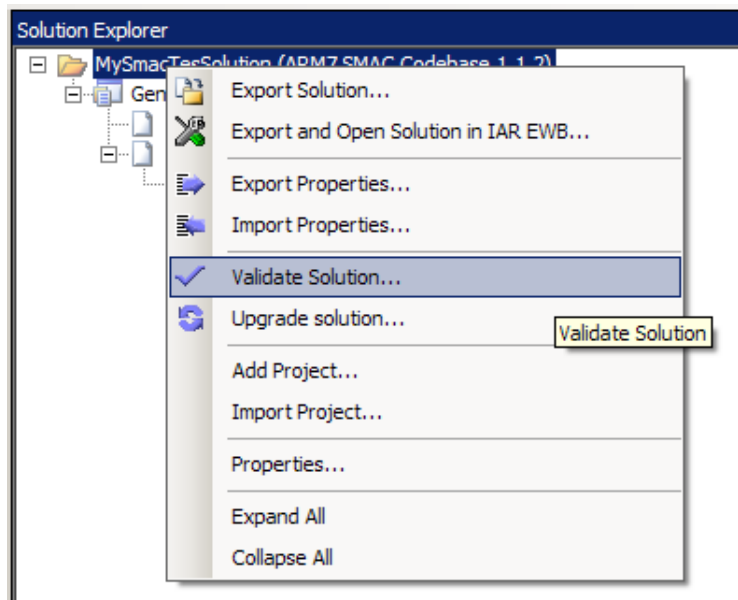


Figure 1-5. Validating a Solution

7. Users must now export the solution as shown in [Figure 1-6](#).

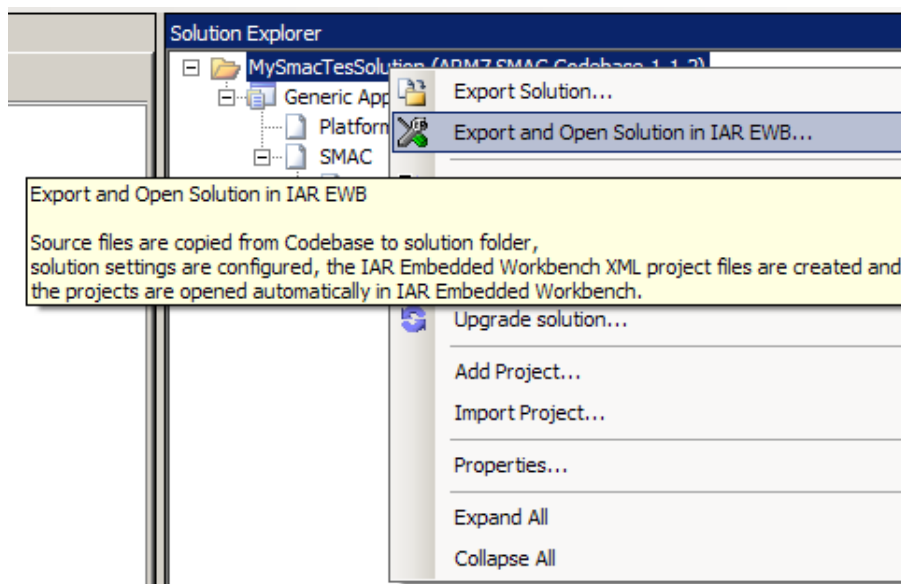


Figure 1-6. Exporting a Solution

1.1 Loading Applications Into a Board Using the JTAG J-Link ARM Debugger

After exporting from BeeKit, the projects are generated as a .eww file. Perform the following tasks to load the application to a board, using the IAR Embedded Workbench IDE. This example uses the repeater application.

1. As shown in Figure 1-7, open the `My Solution.eww` file.

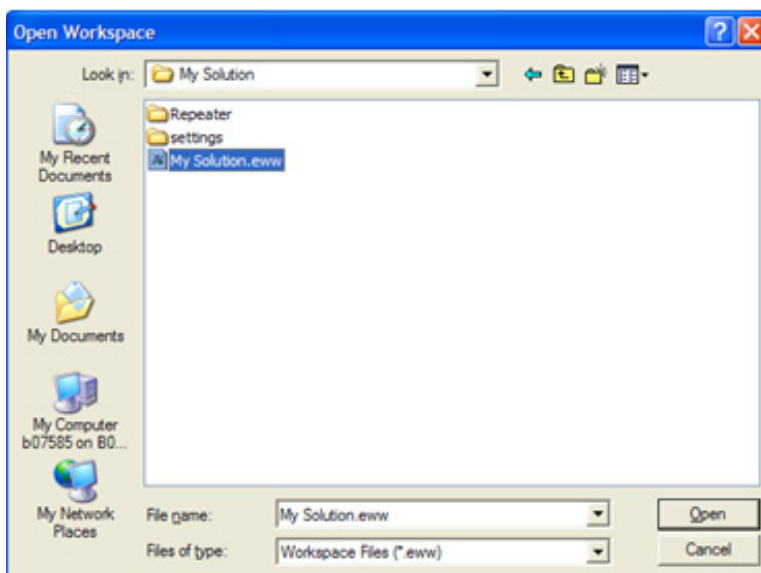


Figure 1-7. Opening a project

2. Make the project by clicking the Make button (Figure 1-8) which is located at the top of the IAR Embedded Workbench main Window as shown in Figure 1-9.



Figure 1-8. Make Button

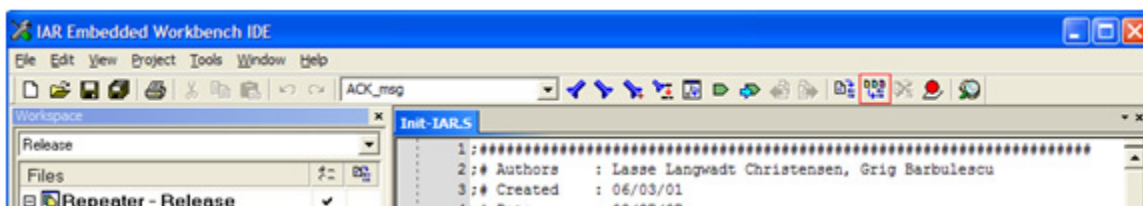


Figure 1-9. IAR Embedded Workbench Main Window

3. Connect the J-Link to the target board.
4. Click the Debug button Figure 1-10 which is located at the top of the IAR Embedded Workbench main window as shown in Figure 1-9.



Figure 1-10. Debug

5. The application will start to download, to run the application press F5 key or click the Go button
Figure 1-11



Figure 1-11. Go

1.2 JTAG Debugging

1. To debug an application select “Debug” at the Work space window as shown in Figure 1-12.

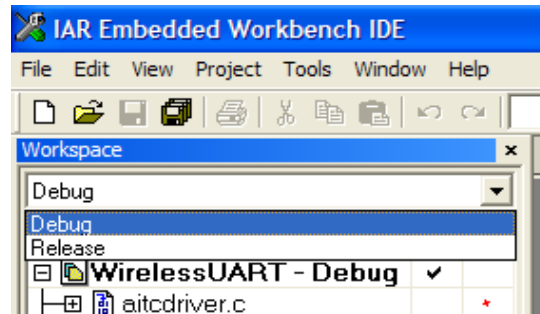


Figure 1-12. IAR Embedded Workbench Work Space Debug and Release Window

2. Right click on the project name and select “Options” as shown in Figure 1-13.

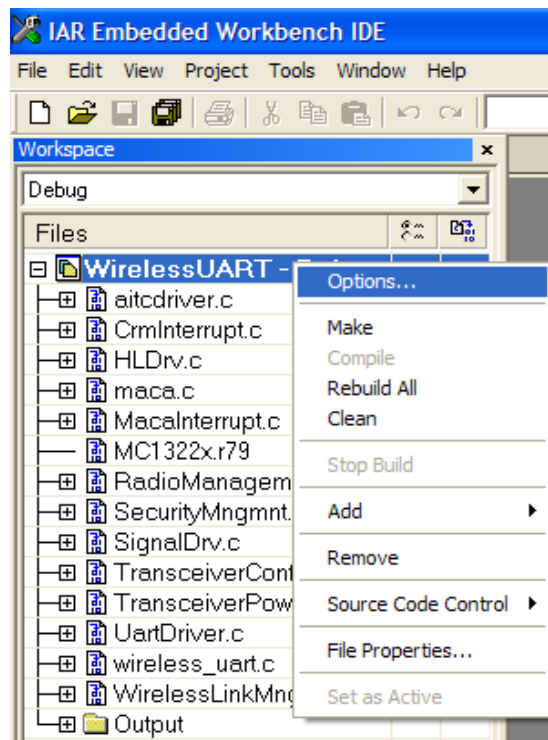


Figure 1-13. IAR Embedded Workbench Options Menu

3. At the debugger category on the Setup tab, select the “J-Link/J-Trace” option as shown in Figure 1-14.

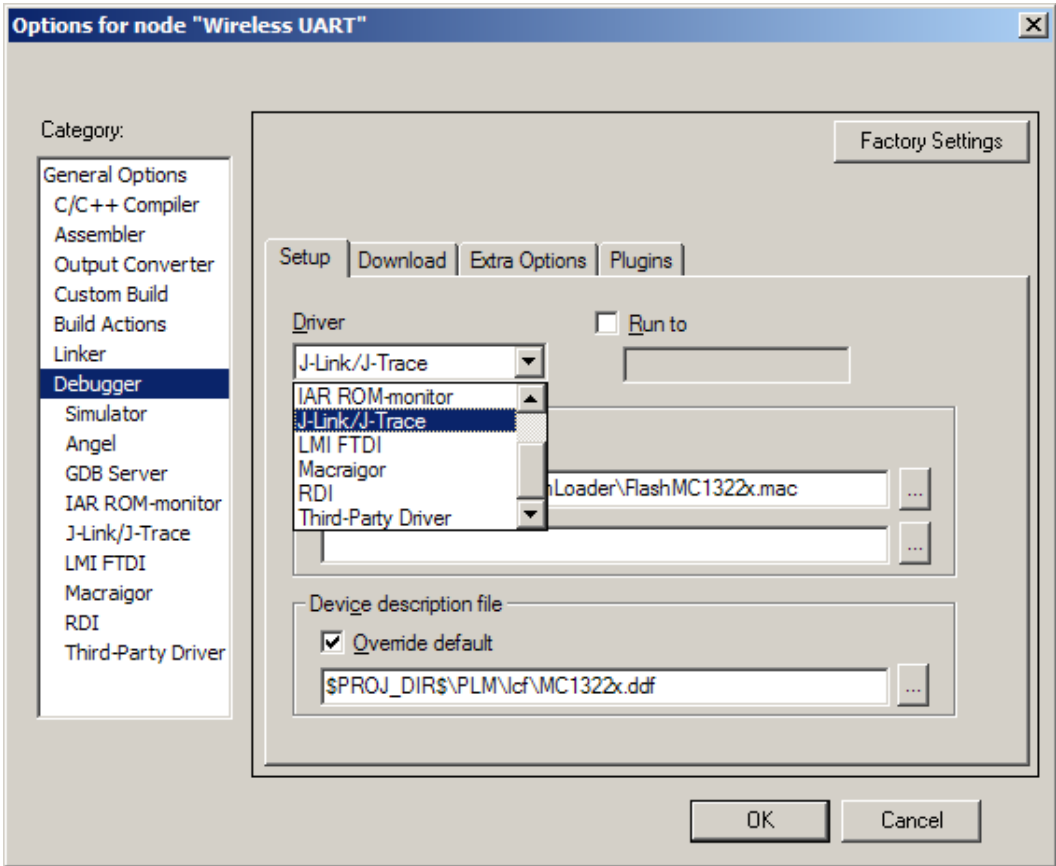


Figure 1-14. Debugger Setup

4. Ensure that the JTAG Debugger is connected to the PC and to the board.
5. On the Project window press the [CTRL]+[D] keys or just click the debug button shown in [Figure 1-15](#) to begin the debugging session.



Figure 1-15. Debug Button

1.3 UART/USB Virtual COM Port Setup

This section describes how to set up a virtual COM port for the following demonstration applications:

- Chapter 2, “Wireless UART Demonstration”
- Chapter 3, “Connectivity Test”
- Chapter 6, “Generic Application Demonstration”
- Chapter 7, “Simple ZigBee Test Client (SZTC) Demonstration”
- Chapter 8, “Repeater Demonstration”
- Chapter 9, “Weather Station Demonstration”
- Chapter 10, “Over The Air Programmer Demonstration”

Attach two boards to two PCs. This allows communication using a PC terminal communications program. The two boards can be attached to two different serial ports of the same PC if needed, but Freescale recommends using two PCs when possible.

1. Connect each of the boards to a separate PC either with an RS-232 cable or a USB cable. If using a USB cable, a corresponding USB driver is required. Freescale recommends a direct USB connection. Do not use a USB hub. This driver is located in the following directory:

```
<INSTALL DIR>\Freescale\Drivers
```

The BeeKit CD image is available from the Freescale ZigBee web site at www.freescale.com/zigbee.

2. To check which COM port is being used by the USB, do the following:
 - a) Open the Windows System Properties window using Start->Settings->Control Panel->System.
 - b) Select the Hardware tab, and click the Device Manager button. The Device Manager window appears as shown in Figure 1-16.

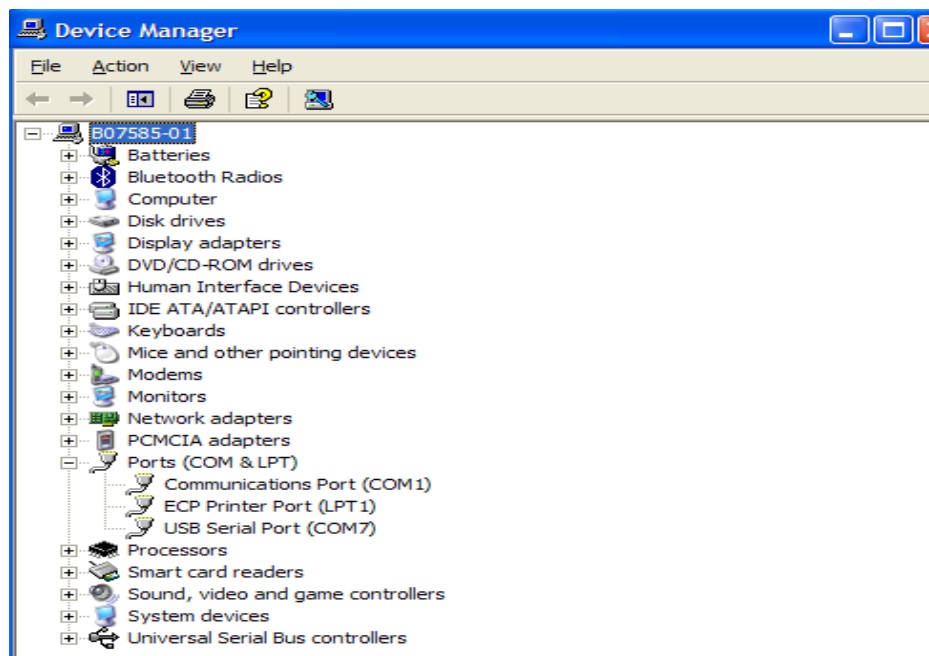


Figure 1-16. COM Port Determination in Device Manager

- c) Scroll to the Ports label and expand the tree by clicking the “+” sign. This shows the COM ports in the system.
 - d) As shown in [Figure 1-16](#), the COM Port chosen by the system is titled USB Serial Port (COM7).
3. If the COM port chosen is not a port numbered between Ports 1-10, then perform the following tasks:
 - a) Double click on USB Serial Port in the Device Manager window. The Properties window appears.
 - b) Select the Port Settings tab, and then click on the Advanced button.
 - c) Go to the COM Port Number drop down menu and select a COM port between 1-10 that is not already in use.
 - d) Open the Windows System Properties window using Start->Settings->Control Panel->System. Select the Hardware tab, and click the Device Manager button. The Device Manager window appears as shown in [Figure 1-16](#).
 - e) Check to ensure the required port appears.
 - f) Close the Device Manager window.
4. Proceed to generating the project in BeeKit as described in the appropriate application chapter.

Chapter 2

Wireless UART Demonstration

The Wireless UART application allows the Freescale ZigBee family of boards to communicate at typematic rates from one board to another over RS-232 cables or USB virtual COM ports. In order to execute this demonstration application the user will need a tool to send and receive characters over two serial ports in addition to what Freescale supply.

This chapter provides a simplified example. Currently, the code cannot be used as a cable replacement. If cable replacement is the ultimate goal, then queues, buffers, and other constructs must be added to increase the reliability and efficiency of this demonstration.

Prior to loading the Wireless UART application, the application must be generated using BeeKit, as described in the *BeeKit Wireless Connectivity Toolkit User's Guide*.

The MC1322x SMAC Wireless UART demonstration application is protocol compatible with previous SMAC Wireless UART applications (those that run on the MC1319x, MC1320x, and MC1321x boards). However, if security is enabled, the MC1322x SMAC Wireless UART demonstration application is incompatible with previous SMAC versions.

See [Section 1.3, “UART/USB Virtual COM Port Setup”](#) for information about how to set up a virtual COM port for this application.

2.1 Generating a Project From BeeKit

Once the UART/USB virtual ports have been configured, continue with generating the project from BeeKit as follows.

1. Open BeeKit (Start->Programs->Freescale BeeKit->Freescale BeeKit).
2. In BeeKit, select the MC1322x SMAC codebase (File menu -> Select Codebase...)
3. Click on File -> New Project and choose the Wireless UART template.
4. Follow the steps as displayed in the New Project wizard.
5. Configure the properties as needed.
6. Validate the solution.
7. Export the solution.
8. BeeKit creates the project folder with the structure as shown in [Figure 2-1](#).

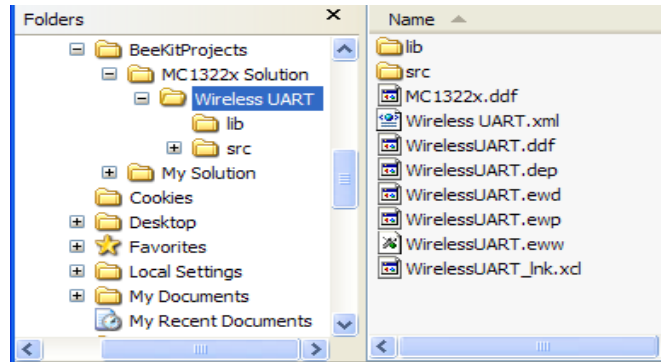


Figure 2-1. BeeKit Created, Wireless UART Directory Structure

For further details about how to use BeeKit, see the *BeeKit Wireless Connectivity Toolkit User's Guide* (BKWCTKUG).

2.2 Open, Compile and Execute the Wireless UART

1. Using the IAR Embedded Workbench, open the Wireless UART work space (Wireless UART.eww) as shown in Figure 2-2.

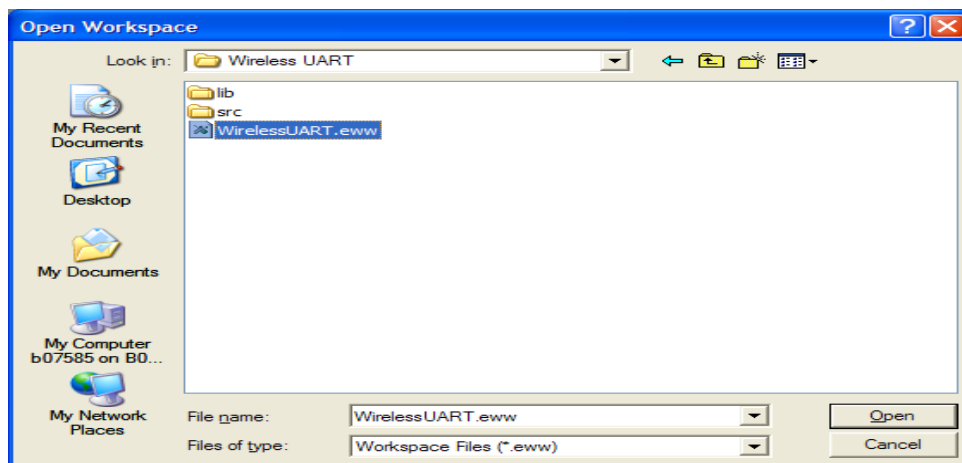


Figure 2-2. Opening Wireless UART Work Space

2. Select "Release" in the Workspace window.
3. Click on Project -> Rebuild All.

The folders Release, Debug, and the settings are now created in the project structure as shown in Figure 2-3.

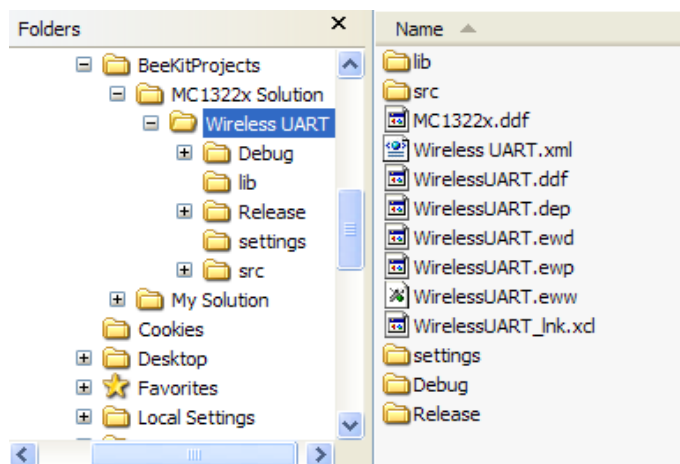


Figure 2-3. Release, Debug, and Settings

The `WirelessUART.bin` file is placed at the following directory location:

```
[Project Directory]\Release\Exe\
```

4. Load the `WirelessUART` application to the boards. Connect the JTAG interface to the board, then click the Debug button on the IAR Embedded Workbench IDE.
5. Use a PC terminal communications program, such as Hyper Terminal, and set the correct baud rate, data bits, parity, COM port, and flow control. Figure 2-4 shows the default MC1322x SMAC RS-232 settings.

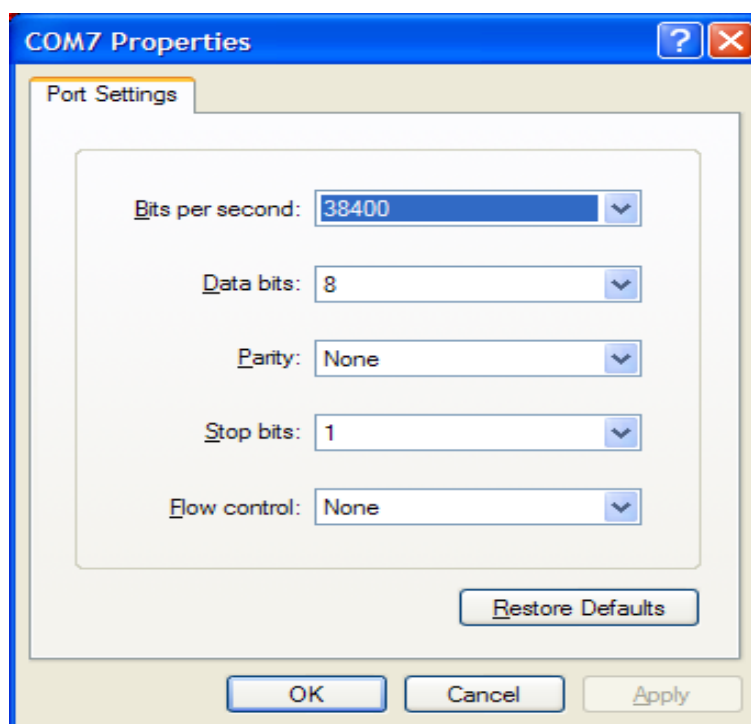


Figure 2-4. Default SMAC RS-232 Settings

6. In the PC terminal program, set the properties in the optional settings as shown in [Figure 2-5](#).

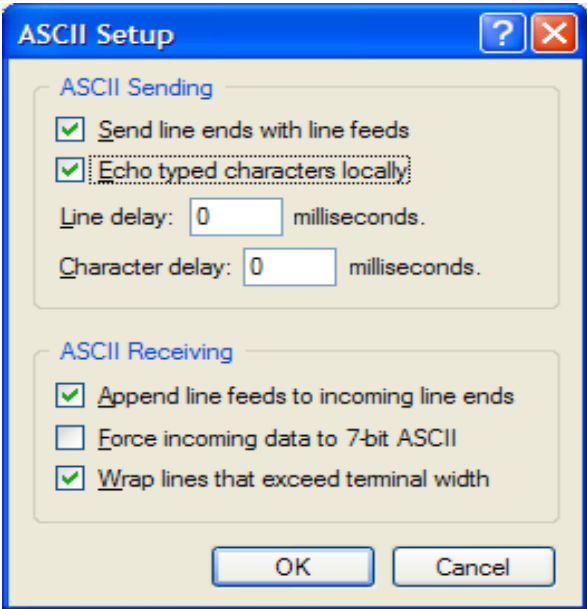


Figure 2-5. Additional Terminal Program Settings

7. Start the serial communication software and send any characters using the keyboard. The other board answers with the “Wireless Typematic Demo.” message as shown in [Figure 2-6](#).

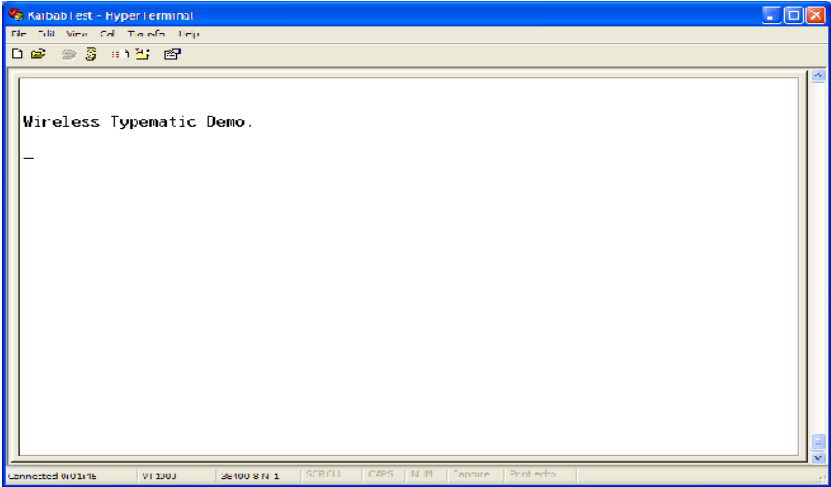


Figure 2-6. Wireless UART Welcome Message

8. Type some characters in the Hyper Terminal Session (Board 1, shown in Figure 2-7) and the typed message appears on the other PC Hyper Terminal Session (Board 2, also shown in Figure 2-7).

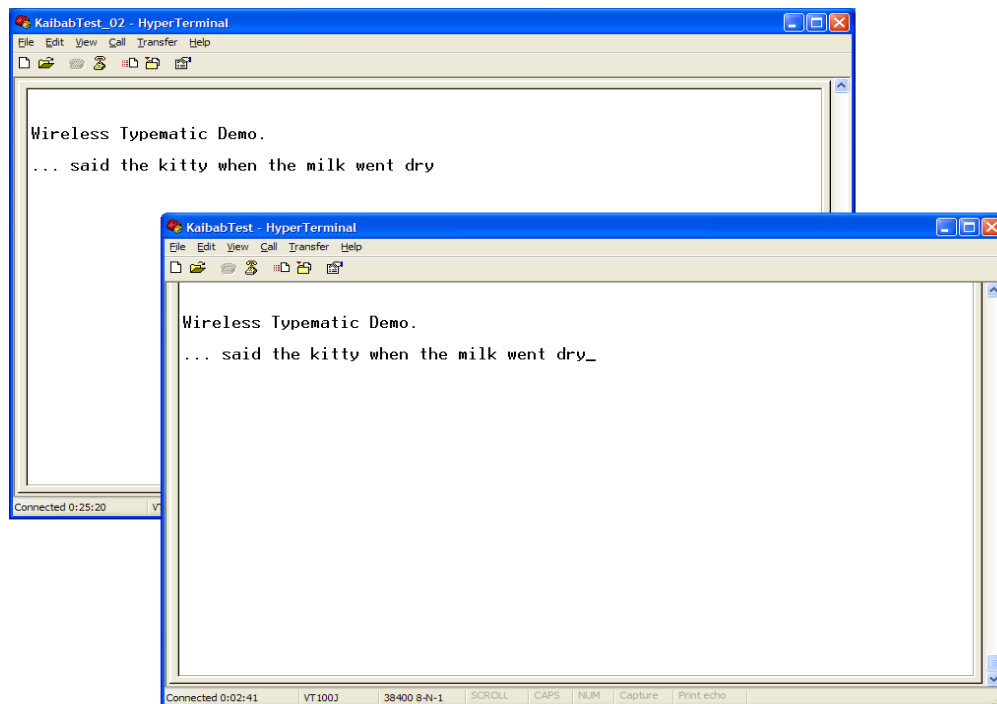


Figure 2-7. Wireless UART Board 1 (Sending) and Board 2 (Receiving)

This is a two-way communication protocol where the boards will retry their packets up to three times if an acknowledgement is not received. This application highlights a very basic MC1322x SMAC Wireless UART implementation and as already stated, because it is a basic demonstration application, it is not intended for large file transfers.



Chapter 3

Connectivity Test

The connectivity test evaluates the basic connectivity between two transceivers. A transmitter and a receiver application are required. The connectivity test supports the following functionality:

- Configure the transceiver in a specific test mode in order to test the transceiver RF performance. These test mode are:
 - Modulated Transmission
 - Unmodulated Transmission
 - Pulse PRBS Transmission
 - IDLE
- Measure the percentage of packet losses over a certain channel as well as the Link Quality Indicator of each packet received.
- Indicate the range of a signal using the Link Quality Indicator.

In both modes parameters such as the channel number and power level can be modified. This allows users to execute all tests in every channel using different power values.

The application includes a reference oscillator frequency output at a pin useful for frequency measurement and adjustment when required.

Two possible interfaces are implemented to use this application: a manual interface through push buttons or menus for a serial interface. Only one interface can be selected, both interfaces can not been working at the same time. The interface type is selected when creating the project with the Freescale BeeKit.

For manual interface, the function of each button is as follows:

- SW1: Selects the application mode. (Channel Change, Power Adjust, Test to perform, etc.) see [Figure 3-1](#).
- SW2: Increases a value.
 - For TX the possible options are: IDLE (0), PSRB (1), PER (2), Range Test TX (3), Continuous Modulated (4) and Continuous Unmodulated (5).
 - For RX mode the possible options are: IDLE (0), Continuous reception (1), PER(2) and Range Test RX (3).
 - The values are momentarily shown at the LEDs then LEDs show current application mode.
- SW3: To decrease the value.
- SW4: To start the test (used only at PER test)

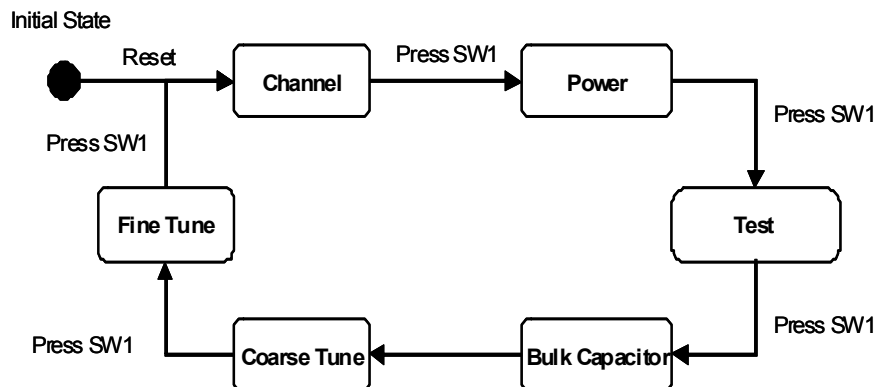


Figure 3-1. Selecting the Application Mode

The functionality of the application could vary according with the selected board. Boards with the serial port and push buttons support both interfaces, however for boards without serial port or without push buttons only one interface is possible.

The following sections describe using the serial interface.

3.1 Loading the Connectivity Application

Prior to loading the Connectivity application, the Connectivity Test application must be generated using BeeKit using the steps shown in [Chapter 1, “Generating an SMAC Application and Port Configuration”](#):

1. Open the [Solution Name].eww file as shown in [Figure 3-2](#).
2. Select Connectivity Test and load this application into two boards as shown in [Section 1.1, “Loading Applications Into a Board Using the JTAG J-Link ARM Debugger”](#).

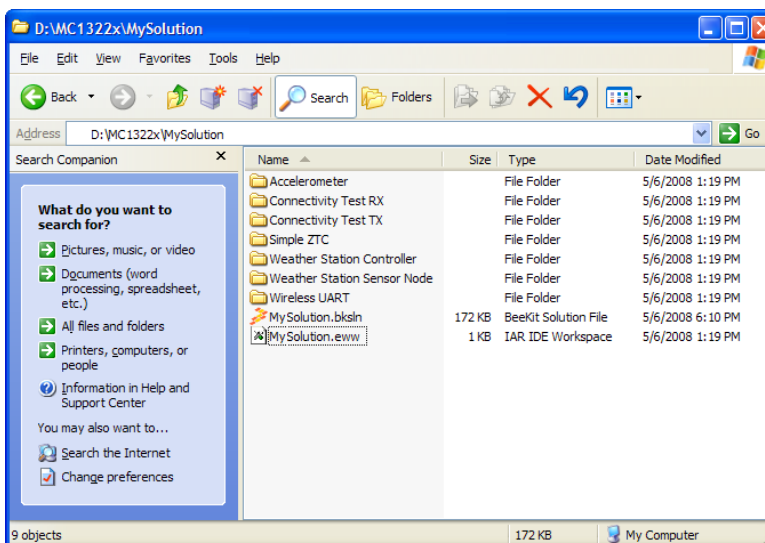


Figure 3-2. My Solution EWW File Location

3.2 UART/USB Virtual Com Port Setup

This section describes how to set up the UART/USB virtual Com port for the Connectivity application.

Figure 3-3 shows the default SMAC RS-232 settings.

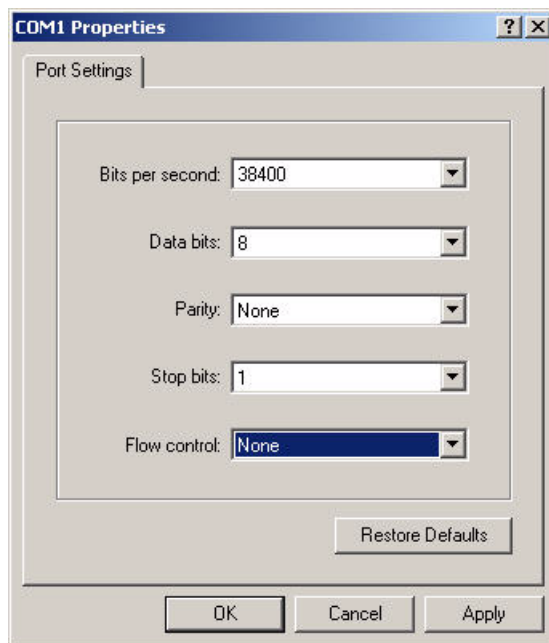


Figure 3-3. Default SMAC RS-232 Setting

1. Use a PC terminal program and set the correct baud rate, data bits, parity, COM port, and flow control as shown in .
2. In the PC terminal program, set the properties in the optional settings as shown in Figure 3-4.

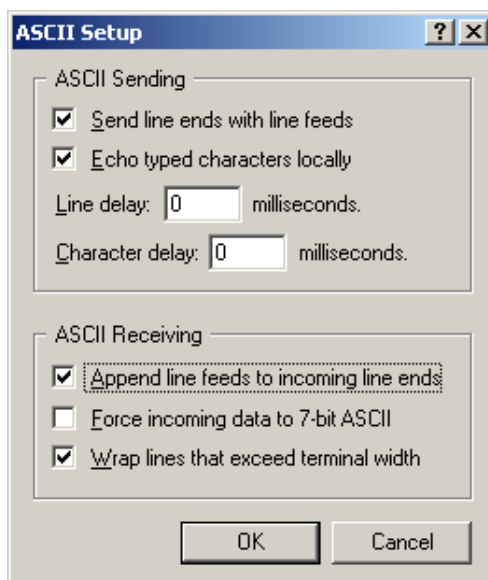


Figure 3-4. Additional Terminal Program Settings

3. Connect the Connectivity Test radio to a USB cable. The USB driver is required. Do not use a USB hub. This driver can be found in the following directory:

```
<INSTALL DIR>\Freescale\Drivers
```

The BeeKit CD image is available from the Freescale ZigBee web site at www.freescale.com/zigbee.

4. See [Section 1.3, “UART/USB Virtual COM Port Setup”](#) for information about how to set up a virtual COM port for this application.

3.3 Starting the Connectivity Test

To start the connectivity test, perform the following tasks:

1. Configure the Com Port as shown in [Section 3.2, “UART/USB Virtual Com Port Setup”](#).
2. Connect each board to a USB cable and a USB port (one PC for each board) and ensure it is enabled as shown in [Section 3.2, “UART/USB Virtual Com Port Setup”](#).
3. Reset both boards.

The terminal appears as shown in [Figure 3-5](#).

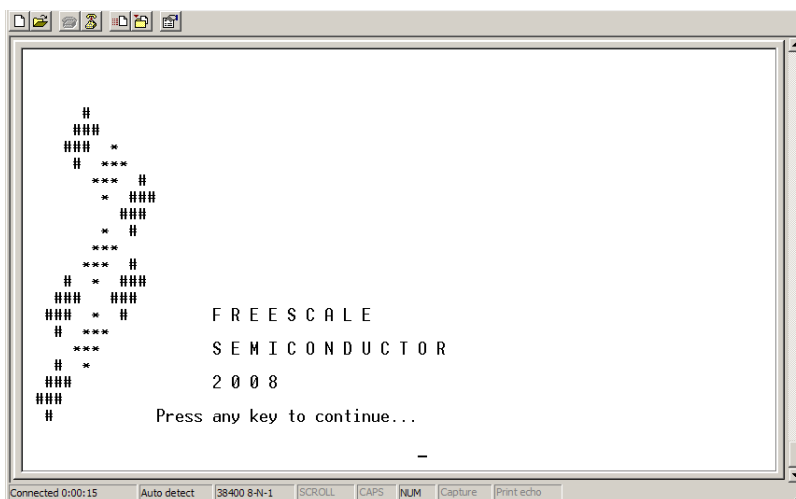


Figure 3-5. Starting the Connectivity Test

1. Press any key and the following text appears.

```
| Connectivity Test Interface |
```

- ```
1 - CHANGE CHANNEL
2 - ADJUST OUTPUT POWER
3 - SELECT TEST MODE
4 - ADJUST CLOCK SETTINGS
```

Note: Case sensitive.

Please select an option:

2. Press the appropriate key to perform the associated task.

Users can set the desired channel or power through this menu. RX and TX mode must be operating on the same channel.

When the “SELECT TEST MODE” (Option 3) is selected, users are routed to a menu to select the operating mode in which the board is going to work (RX or TX) , this menu option is displayed as shown in [Figure 3-6](#).

```

TX / RX Menu |

R - RECEIVER MODE
T - TRANSMITTER MODE
p - Previous Menu

```

Please select an option:

Figure 3-6. TX / RX Menu

After setting up the mode in which the board is going to work, the menu appears as shown in [Figure 3-7](#). The Connectivity test options are described in detail in [Section 3.4, “Connectivity Test Applications”](#).

|                                                                                                                                                                                                                                                                                                            |                                                                                                                                                                                                                                                                                                                                    |
|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| <pre> TX / RX Menu    R - RECEIVER MODE T - TRANSMITTER MODE p - Previous Menu  Please select an option: R  Reception Tests Menu  Current Test Mode: IDLE MODE  I - IDLE R - RECEPTION P - PACKET ERROR RATE RECEIVER r - RANGE TEST RECEIVER p - Previous Menu  Please select an option:           </pre> | <pre> TX / RX Menu    R - RECEIVER MODE T - TRANSMITTER MODE p - Previous Menu  Please select an option: T  Transmission Tests Menu  Current Test Mode: IDLE MODE  I - IDLE T - CONTINUOUS TRANSMISSION P - PACKET ERROR RATE TRANSMITTER r - RANGE TEST TRANSMITTER p - Previous Menu  Please select an option:            </pre> |
|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|

Figure 3-7. Test Mode Menu (Receive on Left, Transmit on Right)

## 3.4 Connectivity Test Applications

The Connectivity Test application combines the Test Mode application, Packet Error Rate (PER) tests, and Range Test applications. The following sections describe each of these tests.

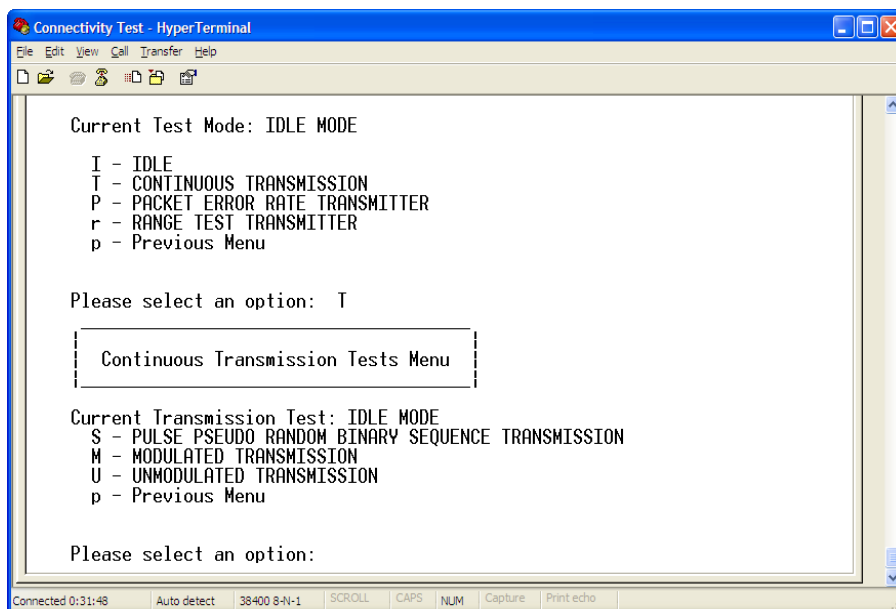
### 3.4.1 Test Mode Application

The Test Mode application allows users to test the RF performance of the transceiver for basic transmitter and receiver tests. The test mode application is a collection of test modes consisting of the following tests:

- Idle
- Transmission 9th Order Binary Polynomial (PRBS9)
- Reception
- Link Quality Indication
- Transmission with modulation
- Transmission without modulation

#### 3.4.1.1 Selecting the Transmit Mode

Figure 3-8 shows the Transmit Test Mode option that allows users to display the current transmit test mode and all the possible tests. To select a test mode, press the appropriate key (S, M, U or P).



**Figure 3-8. Transmission Test Mode Menu**

To test the receiver, the TX board must continuously transmit a packet on the same channel that the RX application is running. The message received while in receive mode is displayed in the Hyper Terminal window as shown in Figure 3-9. In this case, the TX board was transmitting the pulse pseudo random binary sequence.



```

Reception Tests Menu

Current Test Mode: CONTINUOUS PULSE PRBS9 TRANSMISSION

I - IDLE
R - RECEPTION
P - PACKET ERROR RATE RECEIVER
r - RANGE TEST RECEIVER
p - Previous Menu

Please select an option: R
Press Q to exit from Continuous Reception Mode
Press any key to start.....w
Received Packet:0xFF 0xC1 0xFB 0xE8 0x4C 0x90 0x72 0x8B 0xE7 0xB3 0x51 0x89 0x63
0xAB 0x23 0x23 0x02 0x84 0x18 0x72 0xAA 0x61 0x2F 0x3B 0x51 0xA8 0xE5 0x37 0x49
0xFB 0xC9 0xCA 0x0C 0x18 0x53 0x2C 0xFD 0x45 0xE3 0x9A 0xE6 0xF1 0x5D 0xB0 0xB6
0x1B 0xB4 0xBE 0x2A 0x50 0xEA 0xE9 0x0E 0x9C 0x4B 0x5E 0x57 0x24 0xCC 0xA1 0xB7
0x59 0xB8 0x87 0x00 0x00 0x00 0x00 0x00

```

Figure 3-9. Receive Test Mode

## 3.4.2 Spectrum Analyzer Captures

The measurements shown in this section are example illustrations of the Test Modes and were captured from a MC1322x-SRB using the F-antenna. These measurements are radiated measurement and not conducted measurements.

### 3.4.2.1 Idle Mode

The Idle Mode captures the noise floor as shown in Figure 3-10.

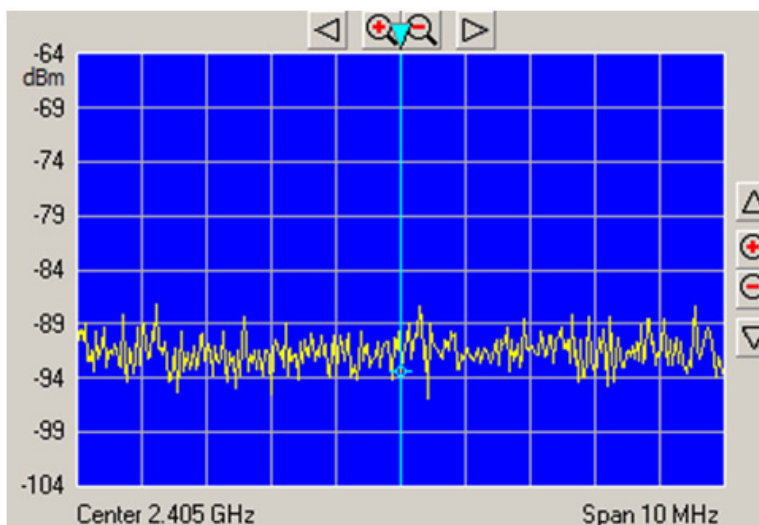


Figure 3-10. Idle Mode Capture

### 3.4.2.2 PRBS9Transmit Mode

The PRBS9 Transmit Mode captures the 9th Order Binary Polynomial as shown in [Figure 3-11](#).

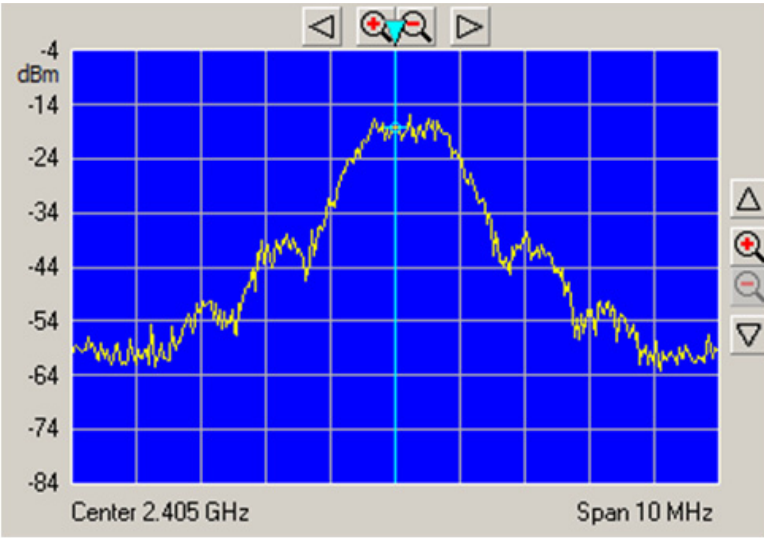


Figure 3-11. PRBS9 TX Mode Capture

### 3.4.2.3 Reception Mode

[Figure 3-12](#) shows the Reception Test Mode. Because the radio is in receive mode, there is little or no energy captured in the selected channel band.

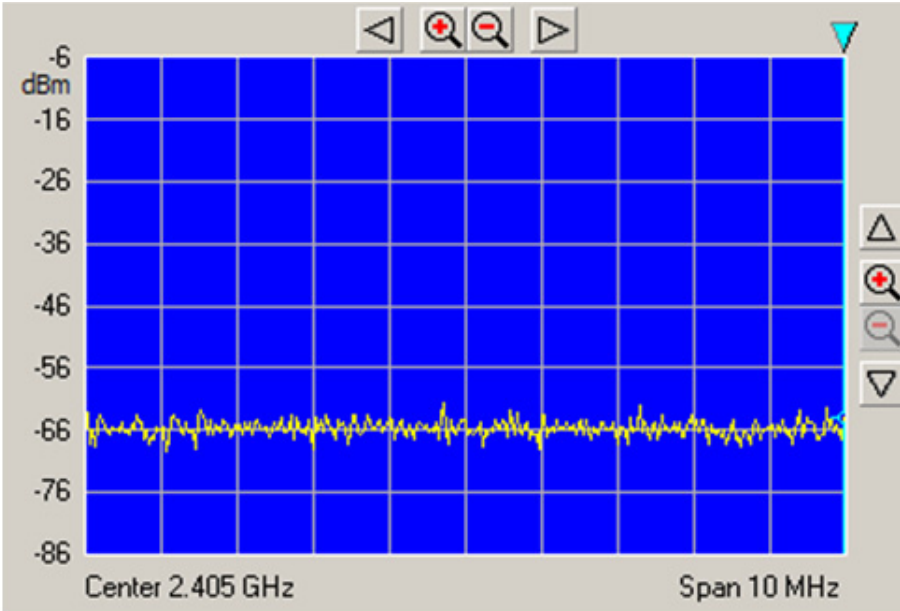


Figure 3-12. Reception Mode Capture

### 3.4.2.4 Transmit with Modulation

Figure 3-13 shows transmitting with modulation.

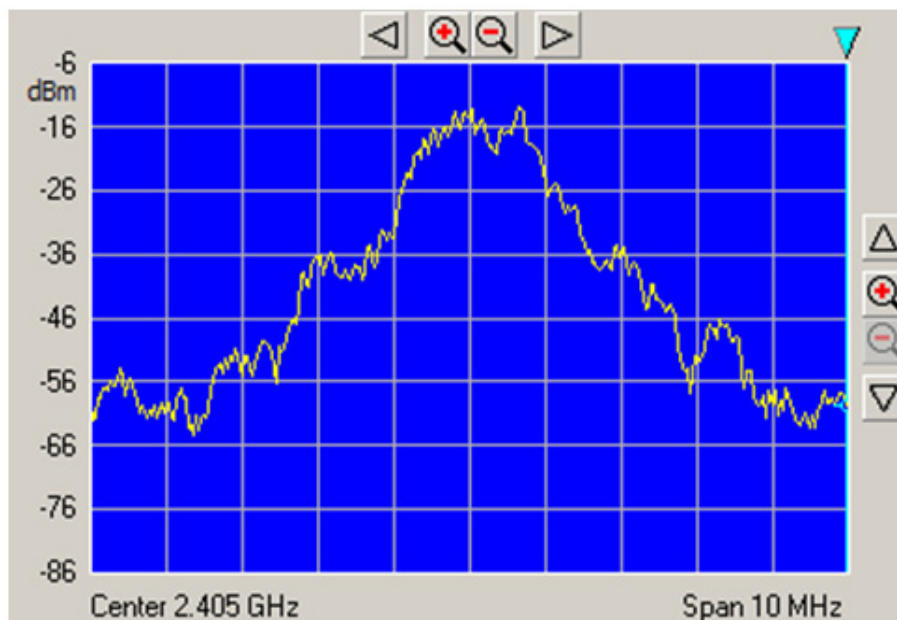


Figure 3-13. TX with modulation Mode Capture

### 3.4.2.5 Transmit without Modulation (CW Mode)

Figure 3-14 shows Continuous Wave (CW) Mode.

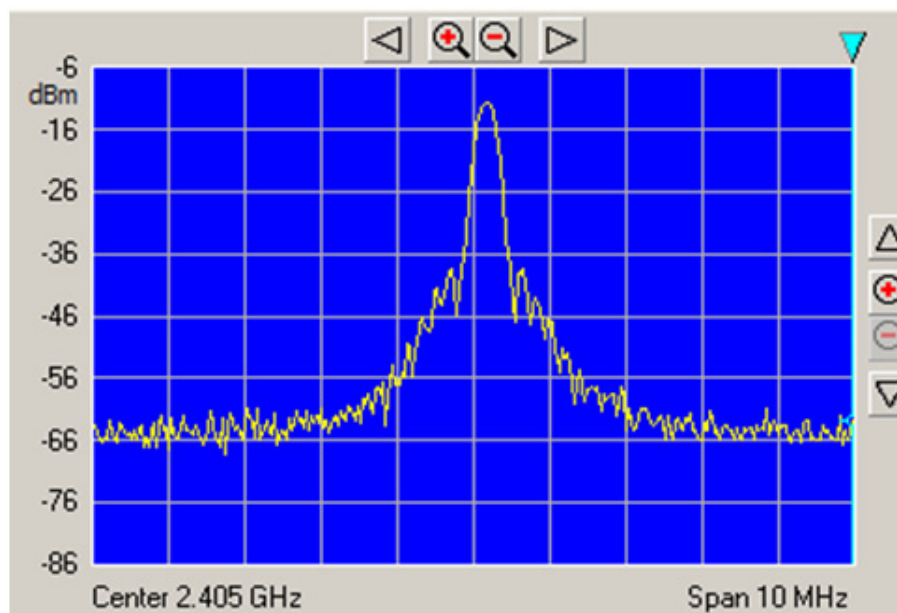


Figure 3-14. TX without modulation Mode Capture

## 3.5 Packet Error Rate (PER) Test

The Packet Error Rate (PER) test is a unidirectional test that sends a number of packets from a transmitter to a receiver all on a single channel. The packet length is 18 bytes of data with 2 bytes of SMAC header for a total of 20 bytes of payload. The results of the packets received by the receiver can be monitored in two ways:

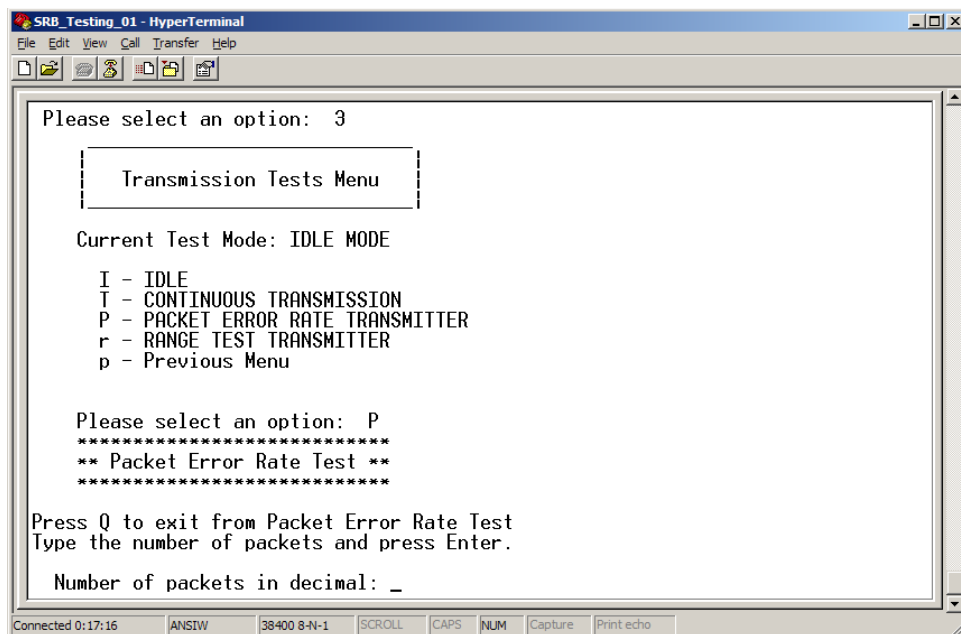
- Using a PC and a USB connection
- In a standalone mode by reading the count on the LEDs on the board

This test allows for PER testing using a PC.

### 3.5.1 Starting the PER Test

Ensure that both the Connectivity Test in TX mode board and the Connectivity Test in RX mode board are on the desired channel. The PER-TX board and the PER-RX board are asynchronous to each other which means that the PER-TX board does not know when the PER-RX board is on. Users must place the PER-RX board into Listen Mode prior to setting the PER-TX board into Transmit Packet Mode. If this is done out of order, the reported packet error rate may be incorrect.

Select Packet Error Rate option on both boards, the Connectivity Test TX and Connectivity Test RX boards, and follow the instructions at the menus see [Figure 3-15](#) for TX and for RX



**Figure 3-15. Selection Packet Error Rate Test**

```

r - RANGE TEST RECEIVER
p - Previous Menu

Please select an option:

** Packet Error Rate Test **

Press Q to exit from Packet Error Rate Test
Press any key to start.....

The RX radio is now listening...
N:000000 L:16 LQI=-31 CRC=1 Data=000102030405060708090A0B0C0D0E0F
N:000001 L:16 LQI=-31 CRC=1 Data=000102030405060708090A0B0C0D0E0F
N:000002 L:16 LQI=-31 CRC=1 Data=000102030405060708090A0B0C0D0E0F
N:000003 L:16 LQI=-31 CRC=1 Data=000102030405060708090A0B0C0D0E0F
N:000004 L:16 LQI=-31 CRC=1 Data=000102030405060708090A0B0C0D0E0F

Good: 000005/000005

Halt

The RX radio is now listening...

```

**Figure 3-16. Reception Mode**

The PER-TX board setup follows a procedure similar to the PER-RX board setup. Place the PER-TX board on the same channel as the PER-RX going through the Connectivity Test Menus. This ensures that the PER-TX board is on the same channel as the PER-RX board. Set PER-TX board to place the application into TX mode. The PER-TX application turns on LEDs 1 through 4 in order to show that the PER-TX board is in Packet Transmit Mode and then it begins to transmit packets.

### 3.5.2 PER operation

Since the PER-TX board and the PER-RX board are on the same channel and the PER-RX board started to listen before the PER-TX board sent any packets, the PER-RX board will toggle LED1 when a packet is being received. Then the PER-TX board blinks LED1 on every packet that is transmitted. If both boards are blinking, then both boards are on the same channel. If only the PER-TX board is toggling LED1, then either the PER-RX board is not in Listen Mode or it is listening to the wrong channel. If this occurs, reset both boards and try the procedure again without switching channels. If a packet is received, the radio echoes data to the PC through the UART connection as shown in [Figure 3-17](#).

- N represents the number of packets received
- L is the length of the packet
- LQI is the Link Quality Indicator (measured in dBm)
- CRC indicates if the Cyclical Redundancy Check (CRC) is good
- Data is the hex formatted payload

```

N:000983 L:16 LQI=-31 CRC=1 Data=000102030405060708090A0B0C0D0E0F
N:000984 L:16 LQI=-31 CRC=1 Data=000102030405060708090A0B0C0D0E0F
N:000985 L:16 LQI=-31 CRC=1 Data=000102030405060708090A0B0C0D0E0F
N:000986 L:16 LQI=-31 CRC=1 Data=000102030405060708090A0B0C0D0E0F
N:000987 L:16 LQI=-31 CRC=1 Data=000102030405060708090A0B0C0D0E0F
N:000988 L:16 LQI=-31 CRC=1 Data=000102030405060708090A0B0C0D0E0F
N:000989 L:16 LQI=-31 CRC=1 Data=000102030405060708090A0B0C0D0E0F
N:000990 L:16 LQI=-31 CRC=1 Data=000102030405060708090A0B0C0D0E0F
N:000991 L:16 LQI=-31 CRC=1 Data=000102030405060708090A0B0C0D0E0F
N:000992 L:16 LQI=-31 CRC=1 Data=000102030405060708090A0B0C0D0E0F
N:000993 L:16 LQI=-31 CRC=1 Data=000102030405060708090A0B0C0D0E0F
N:000994 L:16 LQI=-31 CRC=1 Data=000102030405060708090A0B0C0D0E0F
N:000995 L:16 LQI=-31 CRC=1 Data=000102030405060708090A0B0C0D0E0F
N:000996 L:16 LQI=-31 CRC=1 Data=000102030405060708090A0B0C0D0E0F
N:000997 L:16 LQI=-31 CRC=1 Data=000102030405060708090A0B0C0D0E0F
N:000998 L:16 LQI=-31 CRC=1 Data=000102030405060708090A0B0C0D0E0F
N:000999 L:16 LQI=-31 CRC=1 Data=000102030405060708090A0B0C0D0E0F

Good: 001000/001000

Halt

The RX radio is now listening..._

```

**Figure 3-17. The UART output during PER test**

When the PER-TX board is done sending 1000 packets, the PER-TX board sends packets with the payload “DONEDONE”. If the PER-RX board receives the “DONEDONE” packet, the application echoes the total number of good packets received. The measured PER is echoed to the terminal in a 999/1000 format. When using manual interface the PER value is echoed to the LEDs on the PER-RX board. For example, if the measured packet received was 983/1000 then at the completion of the test, the value 1001b (9d), 1000b (8d), 0011b (3d) will blink. This example allows PER to be measured without the need for a PC.

## 3.6 Range Test

The range test uses the LQI in order to monitor the variation of distance between the transmitter and the receiver in a normal transmission. This test uses two devices one configured as transmitter and the other as receiver.

In the range test, the transmitter sends a message and waits for an acknowledge packet, then the receptor calculates the LQI of the received packet and sent it to the transmitter into the acknowledge packet. In both devices (transmitter and receiver) the LQI value is indicated through LEDs in the manual interface, when serial interface is used the LQI value is sent to the serial terminal. This process is repeated until the user finishes the test. See [Figure 3-18](#)

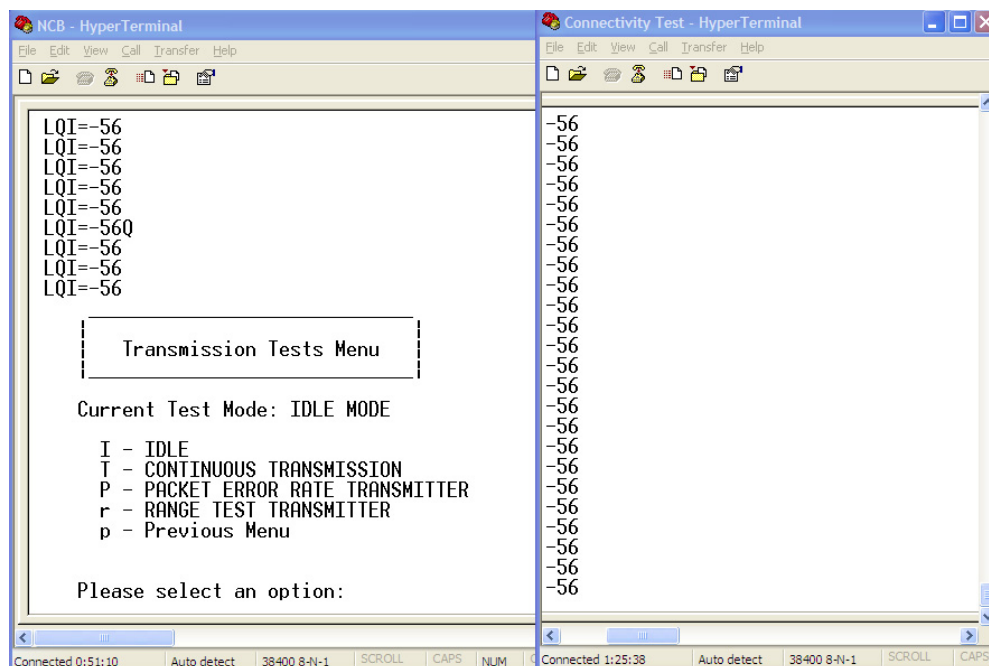


Figure 3-18. Range Test Stop and Start

## 3.7 Crystal Adjustment

The Connectivity Test application includes a utility to help adjust the onboard trim capacitance for the MC1322x 24 MHz crystal reference oscillator. The trim capacitance can be changed to center the oscillator frequency on the target 24 MHz, thus minimizing the error frequency (in ppm).

### NOTE

For more information on tuning the oscillator, see the MC1322x Reference Manual.

The reference frequency cannot be monitored directly via a GPIO pin, so as a substitute, the application provides 2 MHz frequency derived from the reference oscillator and makes it available on the TMR1 signal pin.

To use this utility the “ADJUST CLOCK SETTINGS” option must be selected from the terminal main menu.

When the “ADJUST CLOCK SETTINGS” option is selected, the terminal displays the following menu.

```

|-----|
Clock Settings Menu

1 - Set Bulk 4 pF CAP.
2 - Adjust COARSE TUNE
3 - Adjust FINE TUNE
p - Previous Menu

```

Please select an option:

There are only two options for the “Set Bulk 4 pF CAP” (bulk capacitor) option:

- Enable the 4 pF capacitor
- Disable the 4 pF capacitor

For the “Adjust COARSE TUNE” and the “Adjust FINE TUNE” options:

- Either the coarse tune or the fine tune is adjusted respectively.
- The user must enter a value for either parameter.
  - The possible values are 0x00 to 0x0F for the coarse tune parameter
  - The possible values are 0x00 to 0x1F for the fine tune parameter.
  - The application verifies that the value entered is between these ranges; if not the value is rejected and the parameter value is not updated.

The crystal frequency adjustment is performed using the provided 2 MHz TMR1 reference signal. Use a frequency counter to measure ppm. The trim should be adjusted typically to less than +/-5 to +/-10 ppm.

#### **NOTE**

The TMR1 pin on the Freescale Network Node Evaluation Board is also used by the LCD control. The LCD cannot be used while the crystal adjustment test is being utilized.



## Chapter 4

# Accelerometer Demonstration

The Accelerometer Demonstration application shows various uses of the Freescale X, Y, and Z axes accelerometers.

### NOTE

When using the 13226-SRB, the Accelerometer Demonstration application is not supported because the 13226-SRB does not have an accelerometer. If users select and export this application in BeeKit, the results will not be accurate.

## 4.1 Loading the Accelerometer Application

1. Flash the Accelerometer Demonstration into two boards. One board must be either a MC1322X Sensor Node (also compatible with 13192-SARD or MC13213-SRB) to provide the X, Y, and Z axes accelerometer data and the other board must have an available UART and be able to connect to a PC. This example uses two MC1322x Sensor Node boards.
2. If users need to run the Accelerometer on different targets, those projects must be generated by BeeKit as described in [Chapter 1, “Generating an SMAC Application and Port Configuration”](#).
3. Download the appropriate target image by following the procedure in [Section 1.1, “Loading Applications Into a Board Using the JTAG J-Link ARM Debugger”](#).

## 4.2 Board Setup

To setup both boards for operation (transmit and receive), perform the steps shown in this section.

## 4.3 Board One Setup (PC\_Radio Board)

1. Connect a Sensor Node Board to the PC using the USB cable included in the kit. (Do not use a hub.)
2. Power on the board by setting the Power Switch to the ON position.
3. Press the Reset Button once. The LEDs are off, but the PC\_Radio application is running and in receive mode.

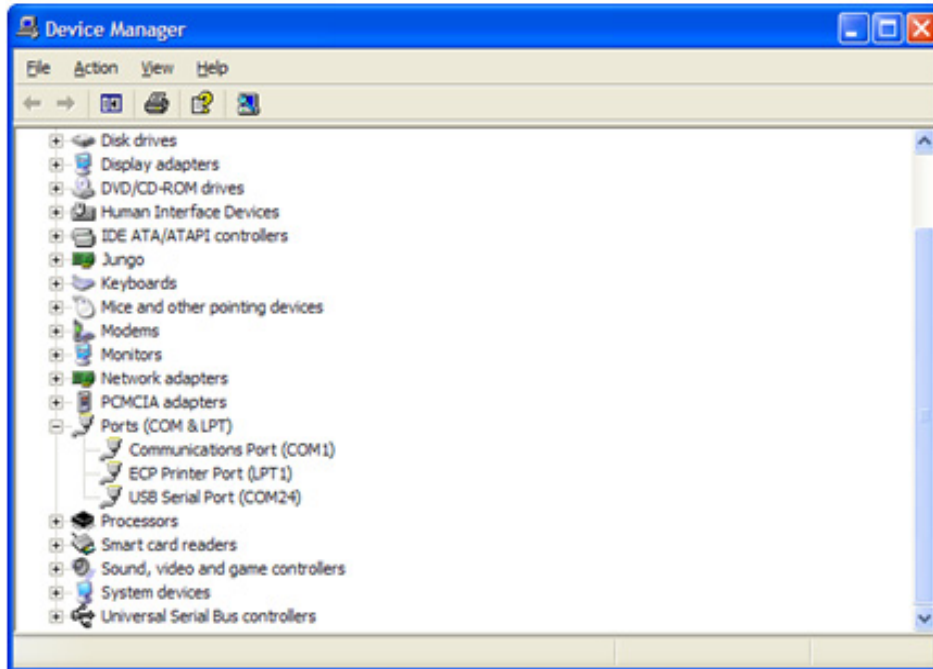
## 4.4 Board Two Setup (Accelerometer Board)

1. Connect 9 VDC power to DC power connector with the 9 VDC wall transformer included in the kit. Power on the board by setting the Power Switch (S100) to the ON position. Another board power option is to use the batteries which provides the advantage of true wireless operation (no cables) and allows users to easily move and manipulate the SRB.
2. Press the Reset Button once.

3. Press button SW1 once and LED3 will momentarily flash to indicate Application Two is running (Accelerometer Mode).
4. The Accelerometer application sends a ping packet to the PC\_Radio every two seconds. This is indicated on the Accelerometer Board by a blinking LED2.
5. The Accelerometer application detects when the Accelerometer Board is moved and quickly toggles LED1, then sends a packet to the PC\_Radio Board with an updated reading.

## 4.5 PC Setup

1. If the Evaluation Kit tools are already installed, then users can run the Triax software by navigating to the link using the Start menu.
2. From Windows, select Start->Programs->Freescale BeeKit->Triax.
  - a) If the Triax application does not exist, go to [Step 3](#) to install it.
  - b) If the application is in the Start Menu, go to [Step 4](#).
3. To run only the Triax application, insert the CD supplied with the kit into the PC CD-ROM drive.
4. Run the `Triax.exe` file from the selected install location on the PC hard drive.
5. The Triax application is set up to run on COM ports 1-10. To check which COM port is being used by the USB, perform the following tasks:
  - a) Open the System Properties window by clicking on Start->Settings->Control Panel->System.
  - b) Select the Hardware tab, and click the Device Manager button. The Device Manager window appears as shown in [Figure 4-1](#).
  - c) Scroll to the “Ports” label and expand the tree by clicking the “+” sign to show the COM ports in the system.
  - d) The COM Port selected by the system is titled `USB Serial Port (COM24)` as shown in [Figure 4-1](#).



**Figure 4-1. COM Port Determination in Device Manager**

6. If the COM port chosen for `Freescall Zigbee/802.15.4 MAC COM Device` is not a port within Ports 1-10, then perform the following tasks:
  - a) Double click on `Freescall Zigbee/802.15.4 MAC COM Device` in the Device Manager window and the Properties window will appear.
  - b) Select the Port Settings tab and then click the Advanced button.
  - c) Go to the Com Port Number drop down menu and select a COM port between 1-10 that is not in use.

## 4.6 Verifying Operation

1. Check for the ping packet. The Accelerometer application sends a ping packet to the PC\_Radio every two (2) seconds as indicated by LED2. The Accelerometer Board quickly blinks LED2 indicating that the ping packet is sent. The PC\_Radio receives the ping and toggles LED2 upon reception. Once connectivity between the PC\_Radio and the Accelerometer Board is verified, go to [Step 2](#).
2. To check if the Accelerometer Board is working, move the Accelerometer Board. LED1 blinks, which indicates that the Accelerometer Board has detected movement.
3. With the default application, data that represents movement of the Accelerometer Board is sent to the PC\_Radio. When the PC\_Radio receives this data, LED2 toggles.
4. Select the Raw Data applet from the Triax application. The Raw Data applet shows the X, Y, and Z axes A/D values as reported by the Accelerometer Board. When the board is laying flat, the raw values should read approximately 0g for both the X and Y axes. However, the Z axis should read approximately 1g. As shown in [Figure 4-2](#), when the Accelerometer Board is moved, the values of the X, Y, and Z axes are updated on the Raw Data applet.

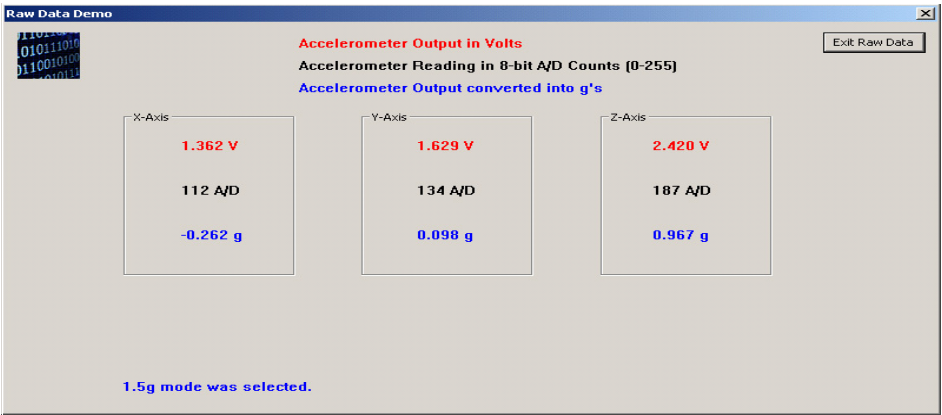


Figure 4-2. Raw Data Demonstration

**NOTE**

To improve accuracy of the accelerometer readings, refer to [Section 4.7](#), “Setting Up the Calibration Application”.

The Triax main window appears as shown in [Figure 4-3](#).



Figure 4-3. Triax Main Window

When the accelerometer is moved, the Accelerometer Board sends data to the PC\_Radio to update its data. Data is only sent when it changes within a small tolerance.

The receiver receives these packets and updates its cached value of the accelerometer data. The PC periodically sends a command string through the USB to the PC\_Radio that requests the accelerometer data. This data is interpreted by the Triax software to enable several applications and demonstrations.

## 4.7 Setting Up the Calibration Application

In order to verify and visualize the calibration procedure, the `Triax.exe` PC GUI must be running, but it is not required.

1. Press the Reset button on the PC\_Radio Board once. (Out of reset, the PC application is running.)
2. Press the Reset button on the Accelerometer Board once.
3. Place the Accelerometer Board on a flat surface. (component side up)
4. Press SW1 on the Accelerometer Board to advance the application to the Accelerometer Mode (Application Two). LED3 momentarily lights to indicate that Application Two is running. The Accelerometer Board sends out a ping packet every two (2) seconds and updates the data on the XYZ Demo PC application each time the board is moved.
5. If the data points for the X, Y, and Z axes shown on the PC GUI are not near the origin of the graph, then continue to [Step 6](#).
6. Press SW4 on the Accelerometer Board once until all LEDs are lit. This shows that the calibration is being performed.
7. Verify that the Accelerometer Board is calibrated by viewing the X, Y, and Z axes on the PC GUI. The squares on the display should be approximately at axis point 0,0. If the calibration is still incorrect, repeat the calibration process until the data points are nominally at axis point 0,0.
8. To quit, exit the application in the GUI and press reset on both boards. Press SW1 on the Accelerometer Board once to return to main application functionality.

## Chapter 5

# Low Power Bell Demonstration

The Low Power Bell Demonstration consists of a transmitter (TX) and receiver (RX). The Low Power Bell TX application serves as the bell switch and demonstrates low power modes and how to implement them. The Low Power Bell RX application serves as the bell and makes a sound when it receives a new packet from the Low Power Bell TX application.

Freescale recommends using the 1322x-LPN Low Power Node to best demonstrate low power capabilities.

### 5.1 Generating the Project From BeeKit

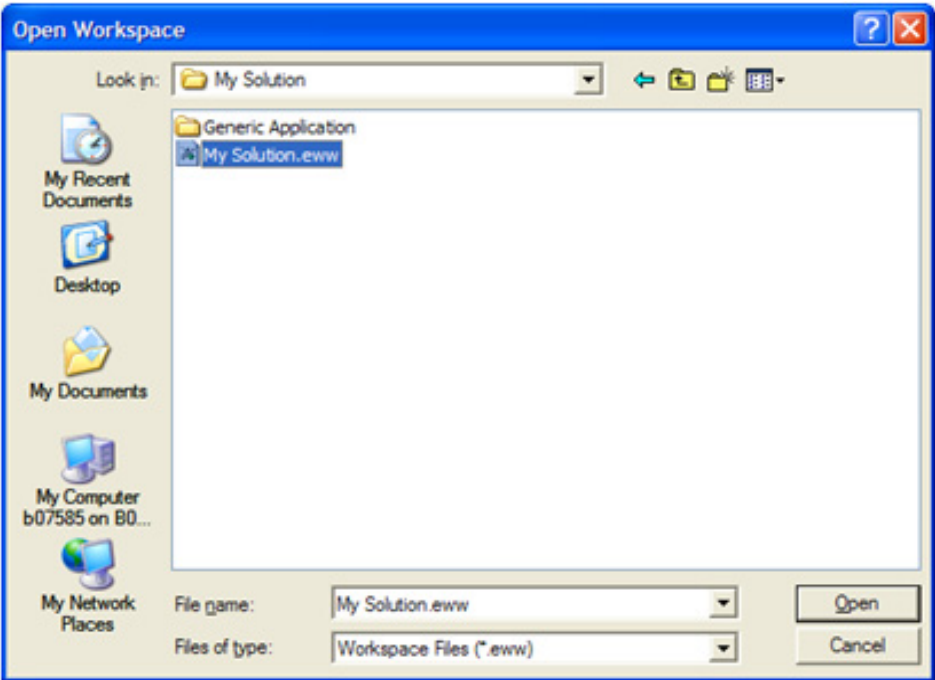
To generate the project from BeeKit.

1. Open BeeKit (Start->Programs->Freescale BeeKit->Freescale BeeKit).
2. In BeeKit, select the MC1322x SMAC codebase (File menu -> Select Codebase...)
3. Click on File -> New Project and choose the Low Power Bell TX template.
4. Follow the steps as displayed in the New Project wizard.
5. Add the Low Power Bell RX project to the current solution.
6. Configure the properties as needed.
7. Be sure to configure the Low Power Bell TX and Low Power Bell RX applications both on the same channel.
8. Validate the solution.
9. Export the solution.

For further details about how to use BeeKit, see the *BeeKit Wireless Connectivity Toolkit User's Guide* (BKWCTKUG).

### 5.2 Open, Compile and Execute the Low Power Bell Application

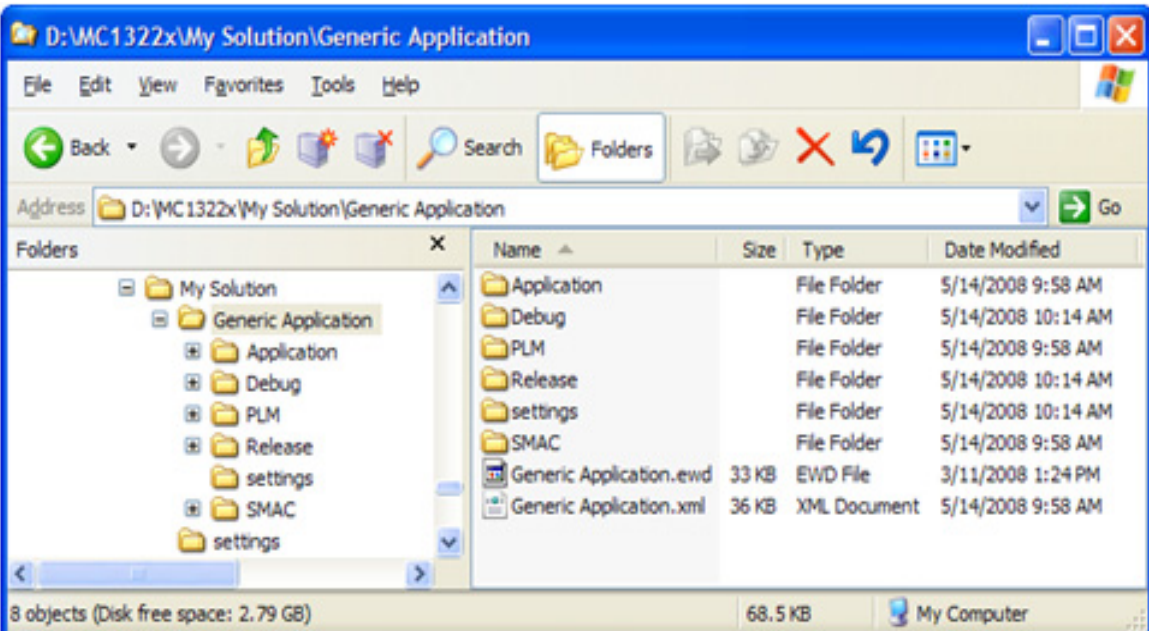
1. Using the IAR Embedded Workbench, open the Generic Application work space (`MySolution.eww`) as shown in [Figure 5-1](#).



**Figure 5-1. Opening Generic Application Space**

2. Chose the “Low Power Bell TX” tab.
3. Select “Release” in the Workspace window.
4. Click on Project -> Rebuild All.

The folders Release, Debug, and the settings are now created in the project structure as shown in Figure 5-2.



**Figure 5-2. Release, Debug, and Settings**



The `Low Power Bell Tx.bin` file is located at the following directory location:

```
[Project Directory]\Release\Exe\
```

5. Use the JTAG interface to load the `Low Power Bell TX` application on the board being used as the Low Power Bell TX. Connect the JTAG interface to the board, then click the Debug button at the IAR Embedded Workbench IDE.
6. Choose the “Low Power Bell RX” tab.
7. Repeat Steps 3 and 4.

The `Low Power Bell RX.bin` file is located at the following directory location:

```
[Project Directory]\Release\Exe\
```

8. Use the JTAG interface to load the `Low Power Bell RX` application on the board being used as the Low Power Bell RX. Click the IAR Debug button to download the application to the board.
9. Reset both boards.

Pressing SW1 on the Low Power TX board sounds the buzzer on the Low Power Bell RX board.



## Chapter 6

# Generic Application Demonstration

The SMAC codebase includes a Generic Application Demonstration that can be used as template to develop proprietary applications. This application shows all the initialization required to start the radio and the commonly used peripherals such as UART and KBIs.

See [Section 1.3, “UART/USB Virtual COM Port Setup”](#) for information about how to set up a virtual COM port for this application.

### 6.1 Generating a Project From BeeKit

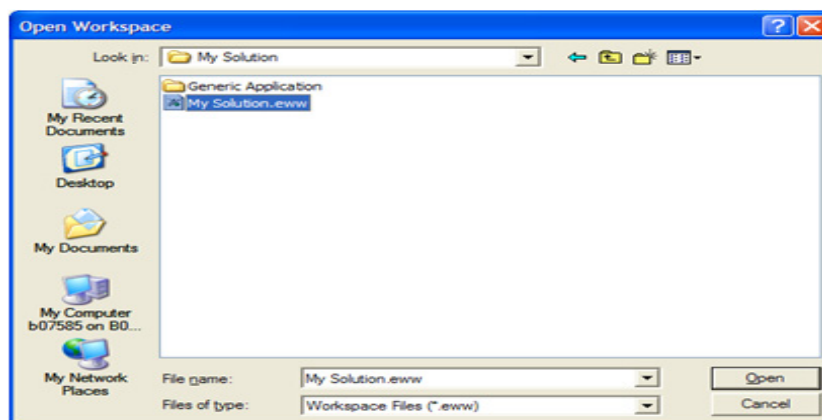
Once the UART/USB virtual ports have been configured, generate the project from BeeKit.

1. Open BeeKit (Start->Programs->Freescale BeeKit->Freescale BeeKit).
2. In BeeKit, select the MC1322x SMAC codebase (File menu -> Select Codebase...)
3. Click on File -> New Project and choose the Generic Application template.
4. Follow the steps as displayed in the New Project wizard.
5. Configure the properties as needed. Choose the manual interface for the KBI.
6. Validate the solution
7. Export the solution.

For further details about how to use BeeKit, see the *BeeKit Wireless Connectivity Toolkit User's Guide* (BKWCTKUG).

### 6.2 Open, Compile and Execute the Generic Application

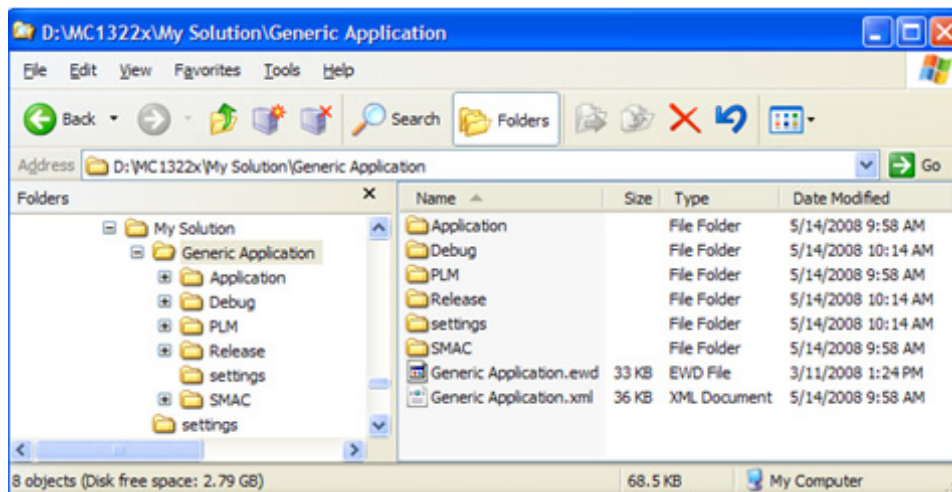
1. Using the IAR Embedded Workbench, open the Generic Application work space (`My Solution.eww`) as shown in [Figure 6-1](#).



**Figure 6-1. Opening Generic Application Space**

2. Select “Release” in the Workspace window.
3. Click on Project -> Rebuild All.

The folders Release, Debug, and the settings are now created in the project structure as shown in Figure 6-2.

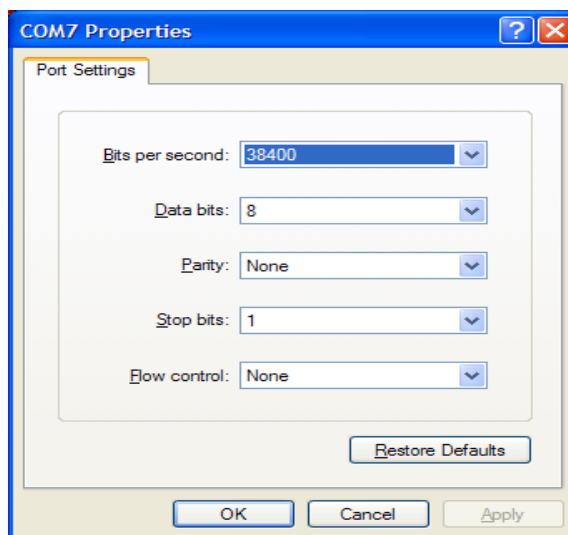


**Figure 6-2. Release, Debug, and Settings**

The WirelessUART.bin file is placed at the following directory location:

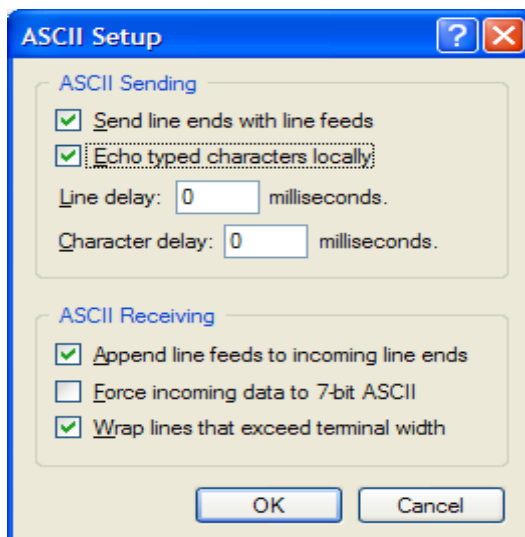
[Project Directory]\Release\Exe\

4. Load the Generic Application file to a board using the JTAG interface. Connect the JTAG interface to the board, then click the Debug button at the IAR Embedded Workbench IDE.
5. Use a PC terminal communications program, such as Hyper Terminal, and set the correct baud rate, data bits, parity, COM port, and flow control. Figure 6-3 shows the default MC1322x SMAC RS232 settings.



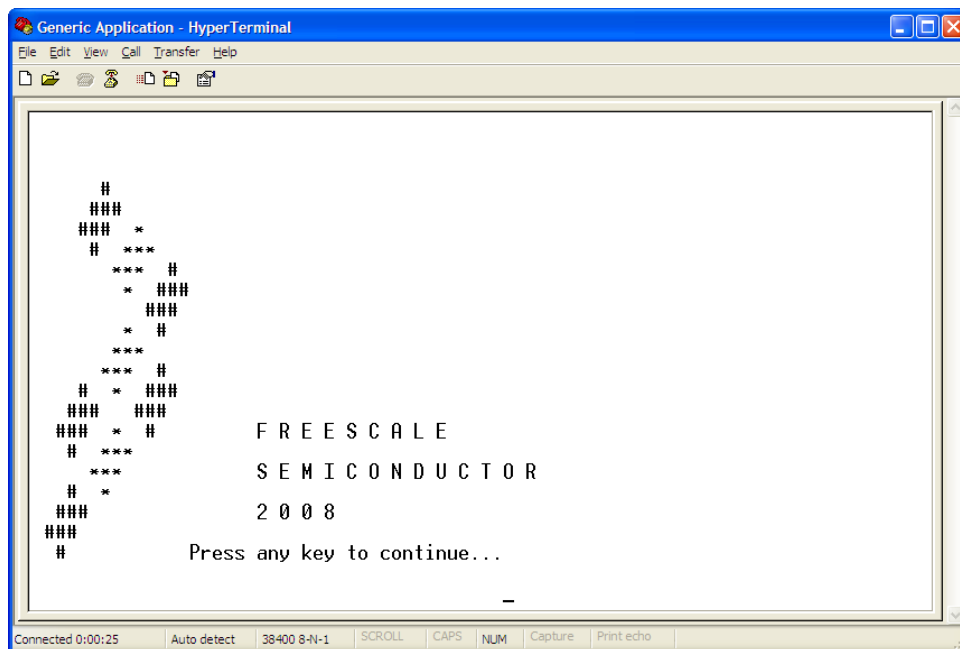
**Figure 6-3. Default SMAC RS-232 Settings**

6. In the PC terminal program, set the properties in the optional settings as shown in [Figure 6-4](#).



**Figure 6-4. Additional Terminal Program Settings**

7. Start the serial communication software and reset the board. Text is displayed in the Hyper Terminal window as shown in the [Figure 6-5](#),



**Figure 6-5. Generic Application Message**

At this point users have an empty project to start their own application.



## Chapter 7

# Simple ZigBee Test Client (SZTC) Demonstration

The Simple ZigBee Test Client (SZTC) application allows users to test the SMAC primitives by sending special data frames through the Serial/USB port. The SZTC application requires two boards and the appropriate Python scripts to communicate with the boards or a serial port packet generator.

Prior to loading the SZTC application, the application must be generated using BeeKit as described in the *BeeKit Wireless Connectivity Toolkit User's Guide*.

See [Section 1.3, “UART/USB Virtual COM Port Setup”](#) for information about how to set up a virtual COM port for this application.

### 7.1 Generating a Project From BeeKit

Once the UART/USB virtual ports have been configured proceed to generate the project from BeeKit.

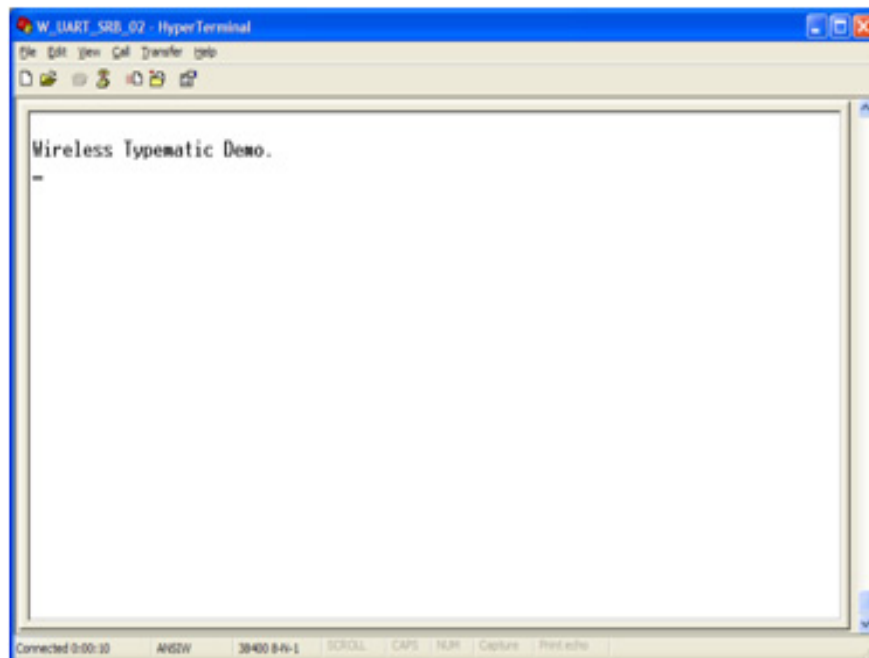
1. Open BeeKit (Start->Programs->Freescale BeeKit->Freescale BeeKit).
2. In BeeKit, select the MC1322x SMAC codebase (File menu -> Select Codebase...)
3. Click on File -> New Project and choose the Simple ZTC template.
4. Follow the steps as displayed in the New Project wizard.
5. Configure the properties as needed.
6. Validate the solution
7. Export the solution.

For further details about how to use BeeKit, see the *BeeKit Wireless Connectivity Toolkit User's Guide* (BKWCTKUG).

### 7.2 Testing the SZTC with the WirelessUART

1. Download the SZTC application to the board that will be used as the tester.
2. Download the WirelessUART application to a board that will be used as the subject of the test.
3. Open a HyperTerminal session (or another compatible communications program) and configure it for serial communications using the following parameters:
  - 8 Bits
  - No Parity
  - 1 Stop
  - 38400 Baud
  - No Flow control

4. Connect the board that is running the WirelessUART application to the serial port of the PC and press that board's reset button. A message appears on the PC display as shown in [Figure 7-1](#).

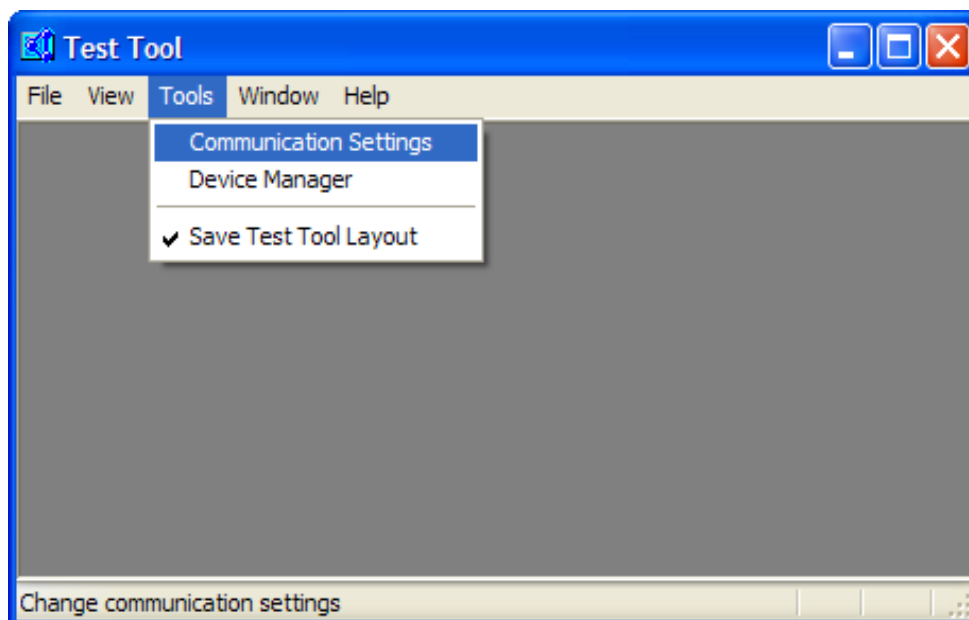


**Figure 7-1. Wireless UART Application**

5. Open the Freescale Test Tool located in the following directory:

Programs\Freescale BeeKit\Test Tool

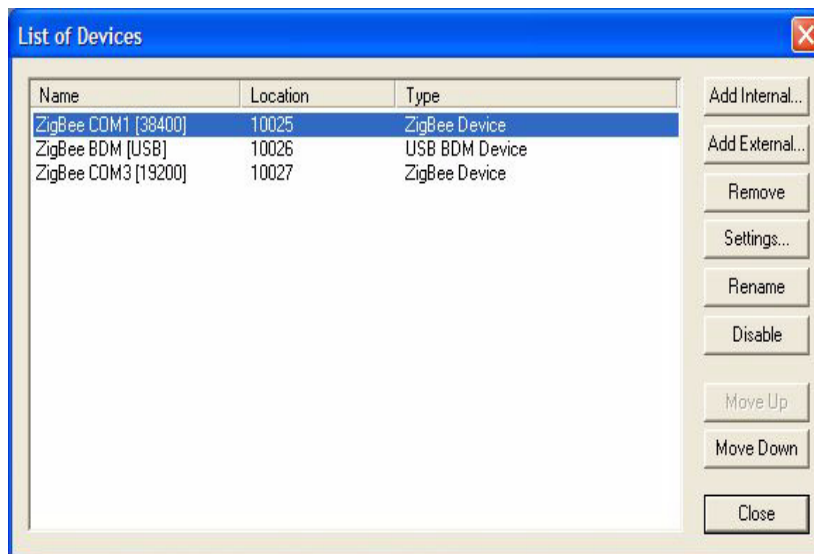
6. As shown in [Figure 7-2](#), from the Test Tool window, select Tools -> Communication Settings.



**Figure 7-2. Test Tool Communication Settings**

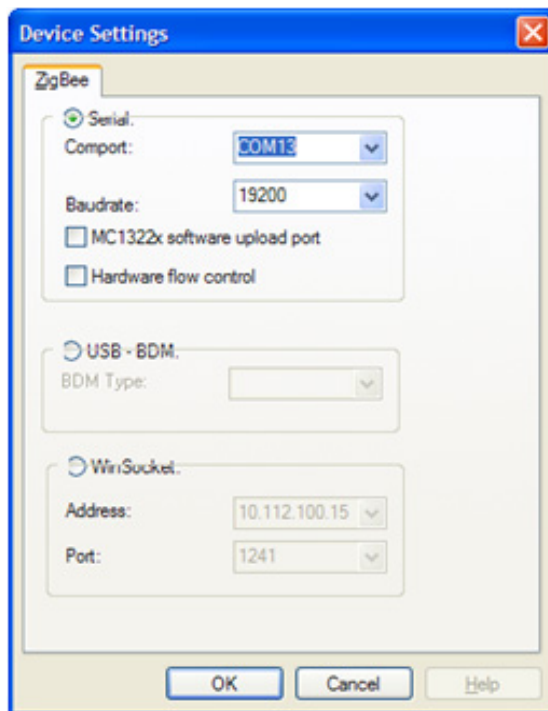


7. Create a new serial connection for the board running the SZTC application by clicking the “Add Internal” button in the “List Of Devices” window as shown in [Figure 7-3](#).



**Figure 7-3. List of Devices Window**

8. Select the appropriate COM port and set the baud rate at 19200 as shown in [Figure 7-4](#).
9. Click the OK button.



**Figure 7-4. Device Settings**

- The List of Devices window appears again as shown in [Figure 7-5](#). Disable all connections except the SZTC connection that was just created by highlighting the connection to be disabled and clicking on the Disable button. The disabled connections are should now be grayed out.

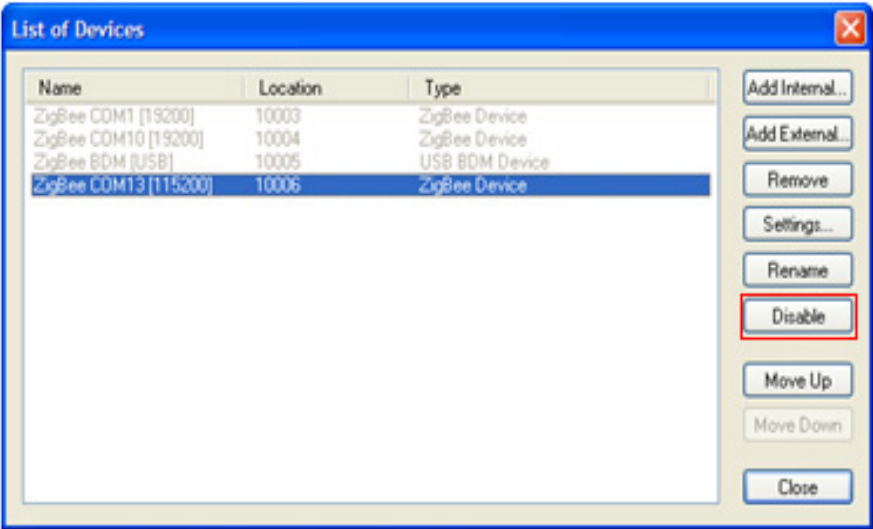


Figure 7-5. Disable Unused Devices

- As shown in [Figure 7-6](#), use the Test Tool main menu to open the Script Server application by clicking on View -> Script Server. See the Freescale *Test Tool User's Guide* for more details about Test Tool.

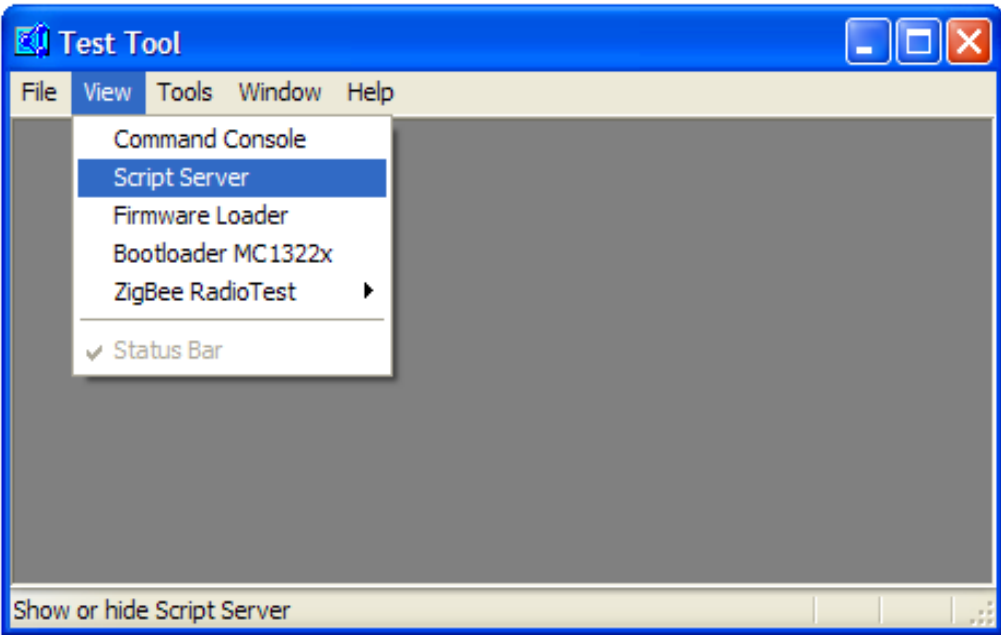
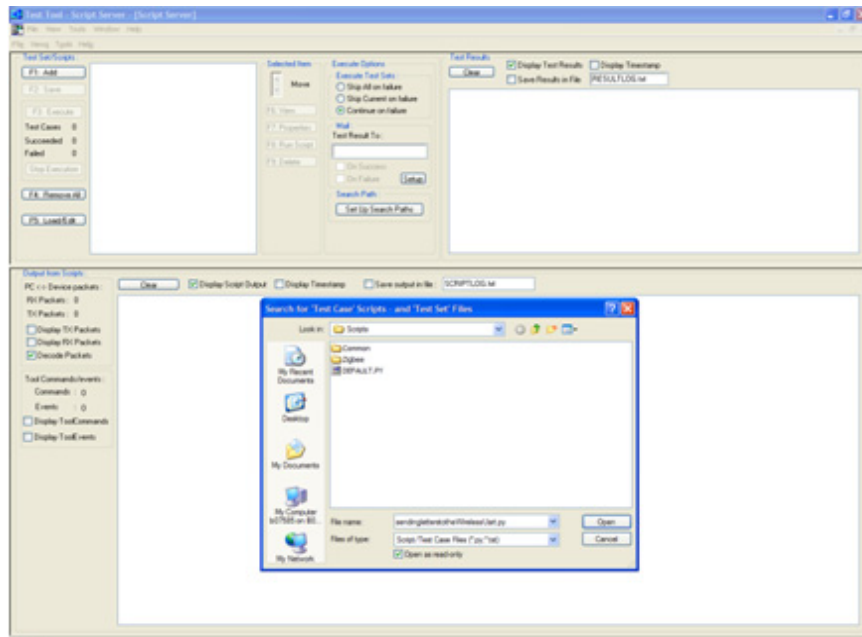


Figure 7-6. Test Tool Launch Script Server

The Script Server window appears as shown in [Figure 7-7](#). See the Freescale *Test Tool User's Guide* for more details about Script Server.

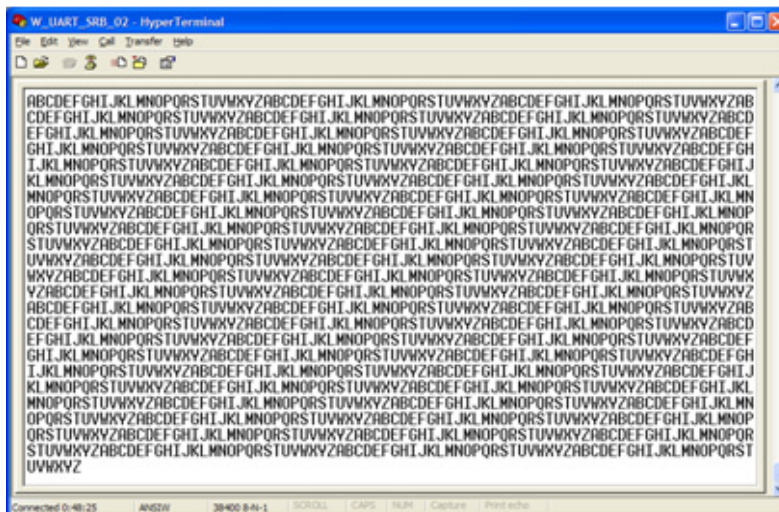


**Figure 7-7. Test Tool Adding a Python (py) script**

12. Load the Sending Letters To The Wireless Uart.py Python script, which is located in the following directory:

```
~\Program Files\Freescale\BeeKit\Test Tool\Scripts\SMAC\Demo Scripts\
```

13. Click on the Execute button to run the script.
14. On the PC running the Serial Terminal application and is connected to the board running the WirelessUART application, the expected end results are shown in [Figure 7-8](#). If this is not the end result, try running the WirelessUART application on the SZTC again.



**Figure 7-8. Result at the Wireless UART Application**



## Chapter 8

# Repeater Demonstration

The Repeater application increases the range between two boards or monitors the activity on an SMAC based communication system. To execute this demonstration application, user need a tool to send and receive characters over two serial ports in addition to what Freescale supplies.

This chapter provides a simplified example. Currently, the code cannot be used as a generic repeater, this application implements two modes of repeater and an SMAC sniffer.

Prior to loading the Repeater demonstration application, the application must be generated using BeeKit, as described in the *BeeKit Wireless Connectivity Toolkit User's Guide*.

The MC1322x SMAC Repeater demonstration application is consistent with previous SMAC Repeater applications (those that run on the MC1319x, MC1320x, and MC1321x boards) but implements a new SMAC sniffer which is a demonstration on how to monitor SMAC communication.

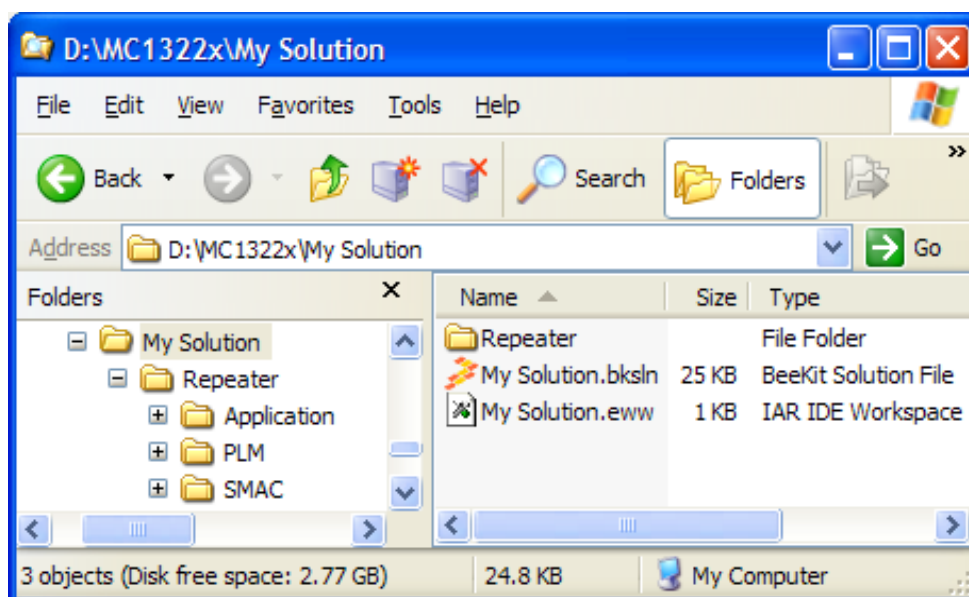
See [Section 1.3, “UART/USB Virtual COM Port Setup”](#) for information about how to set up a virtual COM port for this application.

### 8.1 Generating a Project From BeeKit

Once the UART/USB virtual ports have been configured proceed to generate the project from BeeKit.

1. Open BeeKit (Start->Programs->Freescale BeeKit->Freescale BeeKit).
2. In BeeKit, select the MC1322x SMAC codebase (File menu -> Select Codebase...)
3. Click on File -> New Project and choose the Repeater template.
4. Follow the steps as displayed in the New Project wizard.
5. Configure the properties as needed.
6. Validate the solution
7. Export the solution.

Create the project folder with the structure as shown in [Figure 8-1](#).

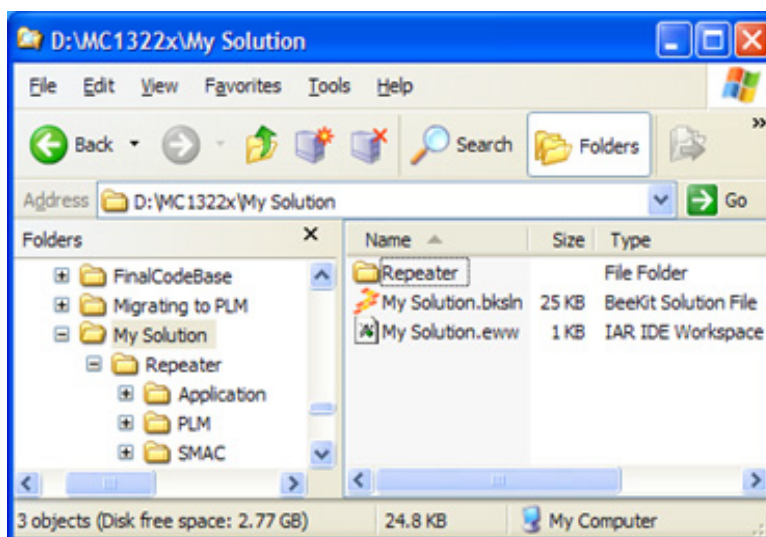


**Figure 8-1. BeeKit Created, Wireless UART Directory Structure**

For further details about how to use BeeKit, see the *BeeKit Wireless Connectivity Toolkit User's Guide* (BKWCTKUG).

## 8.2 Open, Compile and Execute the Repeater

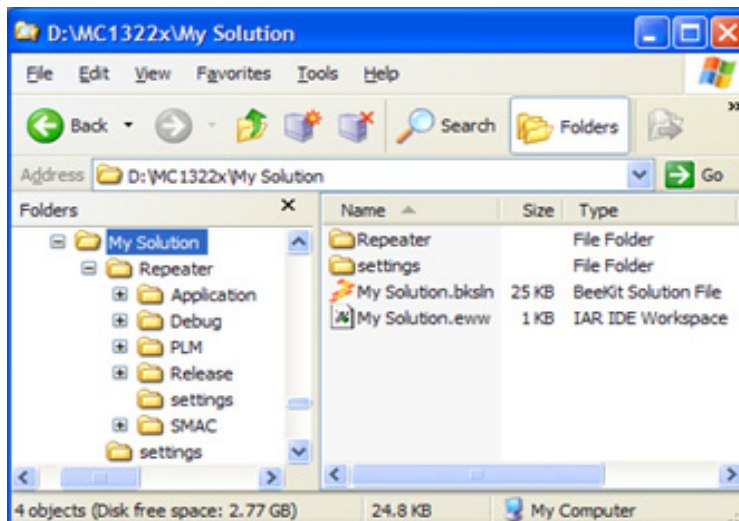
1. Using the IAR Embedded Workbench, open the Repeater work space (`My Solution.eww`) as shown in [Figure 8-2](#).



**Figure 8-2. Opening Repeater Work Space**

2. Select “Release” in the Workspace window.
3. Click on Project -> Rebuild All.

The folders Release, Debug, and the settings are now created in the project structure as shown in Figure 8-3.

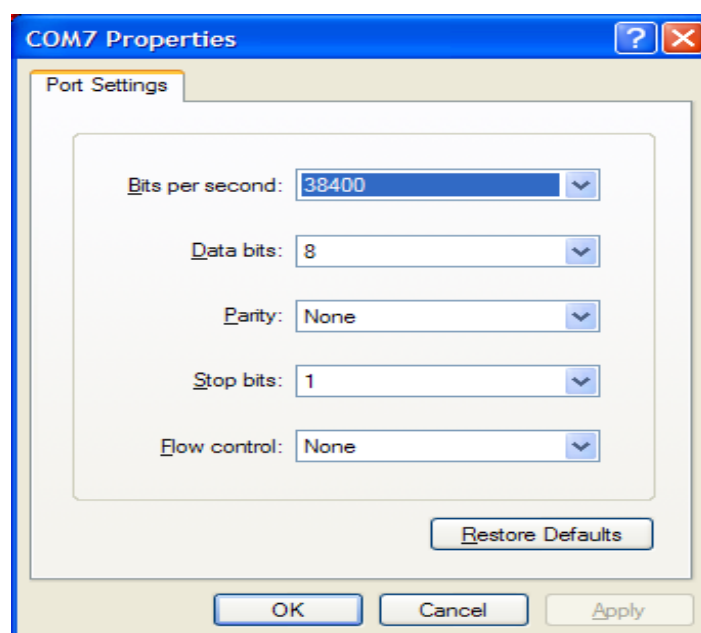


**Figure 8-3. Release, Debug, and Settings**

The Repeater.bin file is placed at the following directory location:

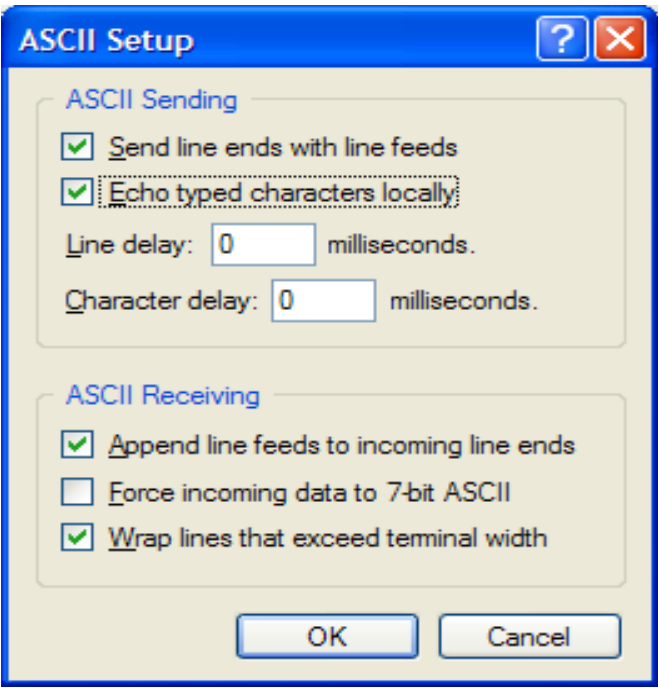
[Project Directory]\Release\Exe\

4. Load the Repeater file to the board. Click the IAR Debug button to download the application to the board.
5. Use a PC terminal communications program, such as Hyper Terminal, and set the correct baud rate, data bits, parity, COM port, and flow control. Figure 8-4 shows the default MC1322x SMAC RS232 settings.



**Figure 8-4. Default SMAC RS-232 Settings**

- In the PC terminal program, set the properties in the optional settings as shown in [Figure 8-5](#).



**Figure 8-5. Additional Terminal Program Settings**

- Start the serial communication software and reset the board. The start window appears as shown in [Figure 8-6](#).



**Figure 8-6. Repeater Start Window**



- Type any key at the serial terminal software and the repeater menu appears as shown in [Figure 8-7](#).

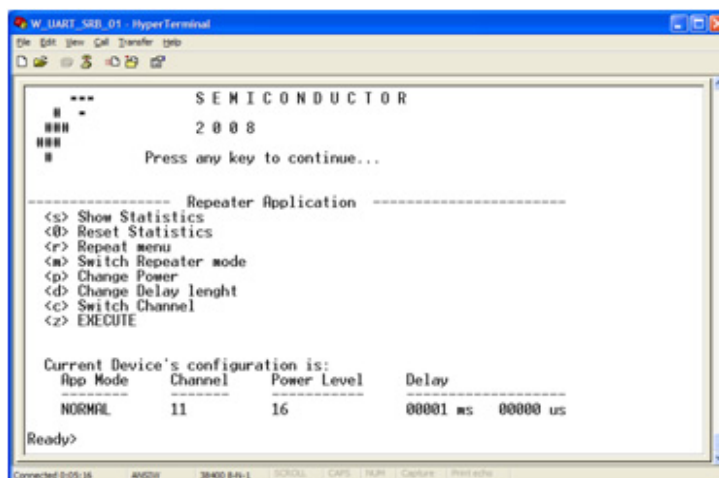


Figure 8-7. Repeater menu and configuration

## 8.3 Repeater Menu, Configuration and Settings

The Repeater menu displays eight options:

```
<s> Show Statistics
<0> Reset Statistics
<r> Repeat menu
<m> Switch Repeater mode
<p> Change Power
<d> Change Delay length
<c> Switch Channel
<z> EXECUTE
```

To select an option, type the character corresponding the desired option on the serial terminal. The options are case sensitive.

- Type “s” to show repeater statistics as shown in [Figure 8-8](#).

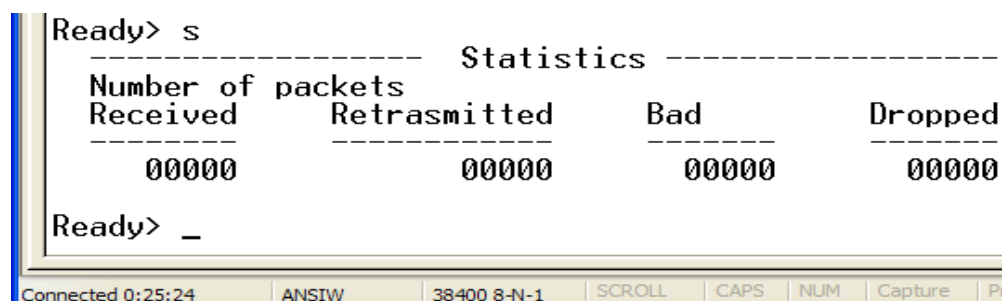


Figure 8-8. Repeater Statistics

Received	The number of frames that have been received.
Retransmitted	The number of frames retransmitted.
Bad	The number of packets received corrupted.

## Repeater Demonstration

**Dropped** The number of frames that has been received but not retransmitted. This is used on the NORMAL mode. Detail about Normal, Dummy, and Sniff modes are covered later in this section.

2. Type “0” (zero) to reset statistics.
3. Type “r” to show repeater’s menu.
4. Type “m” to switch between repeater’s operational modes: NORMAL, DUMMY and SNIFF.

**Normal** The application receives a message and wait “Delay Length“ to receive other messages before retransmitting. If a second message is received, the original received packet is dropped and not retransmitted.

**Dummy** Anything that is received is retransmitted as soon as possible.

**Sniff** The application shows the messages received and does not retransmit anything.

5. Type “p” to change radio’s output power. The power increases each time “p” is typed until the maximum value is reached. When the maximum value is reached, it resets to the minimum value and begins increasing again. See [Figure 8-9](#).

```

W_UART_SER_01 - HyperTerminal
File Edit View Call Transfer Help
[Icons]

Current Device's configuration is:
App Mode Channel Power Level Delay

NORMAL 11 17 00001 ms 00000 us

Ready> p
Current Device's configuration is:
App Mode Channel Power Level Delay

NORMAL 11 18 00001 ms 00000 us

Ready> p
Current Device's configuration is:
App Mode Channel Power Level Delay

NORMAL 11 19 00001 ms 00000 us

Ready> p
Current Device's configuration is:
App Mode Channel Power Level Delay

NORMAL 11 00 00001 ms 00000 us

Ready>
Connected 0:38:56 AN620R 38400 8-N-1 [CTS] [RTS] Capture Print editor

```

**Figure 8-9. Power output adjustment**

6. Type “d” to change the “Delay Length“ value. See [Figure 8-10](#).

```

W_UART_SER_01 - HyperTerminal
File Edit View Call Transfer Help
[Icons]

<d> Change Delay lenght
<c> Switch Channel
<z> EXECUTE

Current Device's configuration is:
App Mode Channel Power Level Delay

NORMAL 11 16 00001 ms 00000 us

Ready> d
Enter delay. First enter the milliseconds and then the microseconds:
how many msec uses (where 00001<value<65535) please write all digits> 00500
Thank you
How many uses (where 005<value<999), please write all three digits (if you do
n't want to use it just write 000)> 040
Thank you

Current Device's configuration is:
App Mode Channel Power Level Delay

NORMAL 11 16 00500 ms 00040 us

Ready>
Connected 0:38:42 AN620R 38400 8-N-1 [CTS] [RTS] Capture Print editor

```

**Figure 8-10. Change Delay Length**

7. Type “c” to switch channel.
8. Press “z” to execute the repeater, to quit press any key.

## 8.4 Running the Repeater Demonstration

1. Configure the repeater settings as needed, as shown in [Section 8.3, “Repeater Menu, Configuration and Settings”](#).
2. To start running the application press “z” at the main menu.
3. To stop the application press any key.

### 8.4.1 Creating a Sniffer

To create a sniffer on Channel 13 set to check for max power, perform the following tasks:

1. Start a serial terminal as shown in [Section 8.2, “Open, Compile and Execute the Repeater”](#).
2. Reset a board with the repeater application flashed.
3. Press “c” key as many times as needed until Channel is set to 13.
4. Press “p” key as many times as needed until Power Level is set to 18.
5. Press “m” key as many times as needed until App Mode is set to SNIFF.
6. Press “z” key to start sniffing Channel 13.
7. Configure any SMAC demonstration application to transmit on Channel 13 and start that application.
8. The over the air packets on Channel 13 will be displayed on the terminal attached to the repeater application.
9. To stop the sniffer, press any key at the terminal interface used by the sniffer application.

### 8.4.2 Running a Dummy Repeater

To run a dummy repeater on channel 11, perform the following tasks.

1. Start a serial terminal as shown in [Section 8.2, “Open, Compile and Execute the Repeater”](#).
2. Reset a board that has the repeater application FLASHED on it.
3. Press “c” key as many times as needed until Channel is set to 11.
4. Press “m” key as many times as needed until App Mode is set to DUMMY.
5. Press “z” key to start the repeater.
6. Use another board configured with the Wireless UART Demo set to Channel 11.
7. Start the Wireless UART application.
8. Each character transmitted shows its echo because the message is being retransmitted by the repeater.
9. To stop the repeater, press any key at the terminal interface used by the repeater application.



## Chapter 9

# Weather Station Demonstration

The Weather Station demonstration application ships as part of the MC1322x Developer Starter Kit and is also included as a demonstration in the BeeKit ARM7 SMAC Codebase. The Weather Station demonstration application simulates some weather station data and shows the use of Freescale sensors for acceleration and pressure. This Weather Station demonstration consists of three components:

- Weather Station Controller using the Network Node
- Weather Station Sensor using the Sensor Node
- Weather Station PC GUI application

This chapter provides a simplified example. Currently, the code does display actual weather station data, but provides simulated data for demonstration purposes only.

Prior to loading the Weather Station demonstration application, the applications must be generated using BeeKit, as described in the *BeeKit Wireless Connectivity Toolkit User's Guide*.

The Weather Station demonstration application was developed for the MC1322x. There are no previous versions for the MC13213-SRB, MC13213-NCB or other Freescale ZigBee legacy boards.

See [Section 1.3, “UART/USB Virtual COM Port Setup”](#) for information about how to set up a virtual COM port for this application.

### NOTE

When using the 13226-SRB, the Weather Station Demonstration application is not supported because the 13226-SRB does not have an accelerometer. If users select and export this application in BeeKit, the results will not be accurate.

## 9.1 Generating a Project From BeeKit

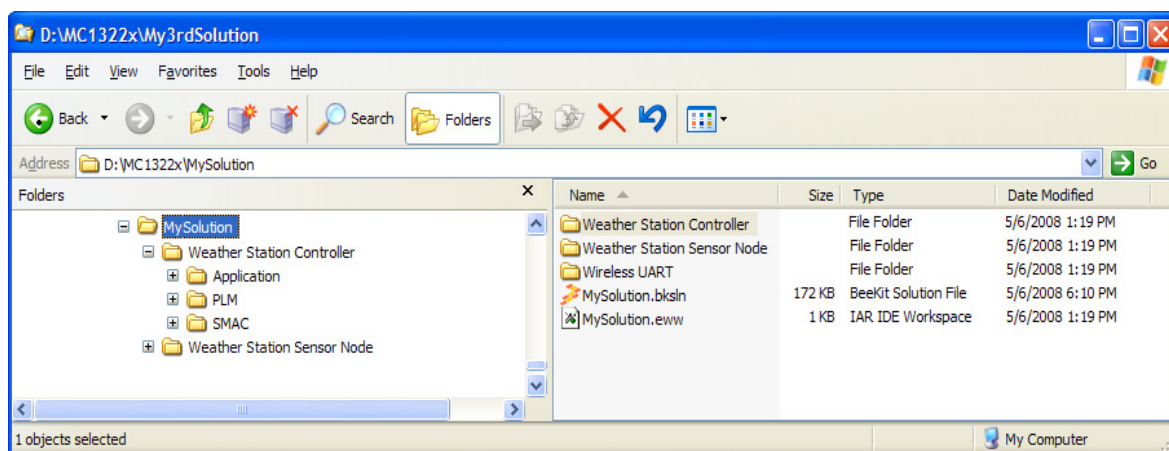
Once the UART/USB virtual ports have been configured proceed to generating the project from BeeKit.

1. Open BeeKit (Start->Programs->Freescale BeeKit->Freescale BeeKit).
2. In BeeKit, select the MC1322x SMAC codebase (File menu -> Select Codebase...)
3. Click on File -> New Project and choose the Weather Station Controller template.
4. Follow the steps as displayed in the New Project wizard.
5. Click on File -> New Project and choose the Weather Station Sensor Node template.
6. Follow the steps as displayed in the New Project wizard.
7. Configure the properties as needed.
8. Validate the solution



- 9. Export the solution.

BeeKit creates the project folder with the structure as shown in Figure 9-1.

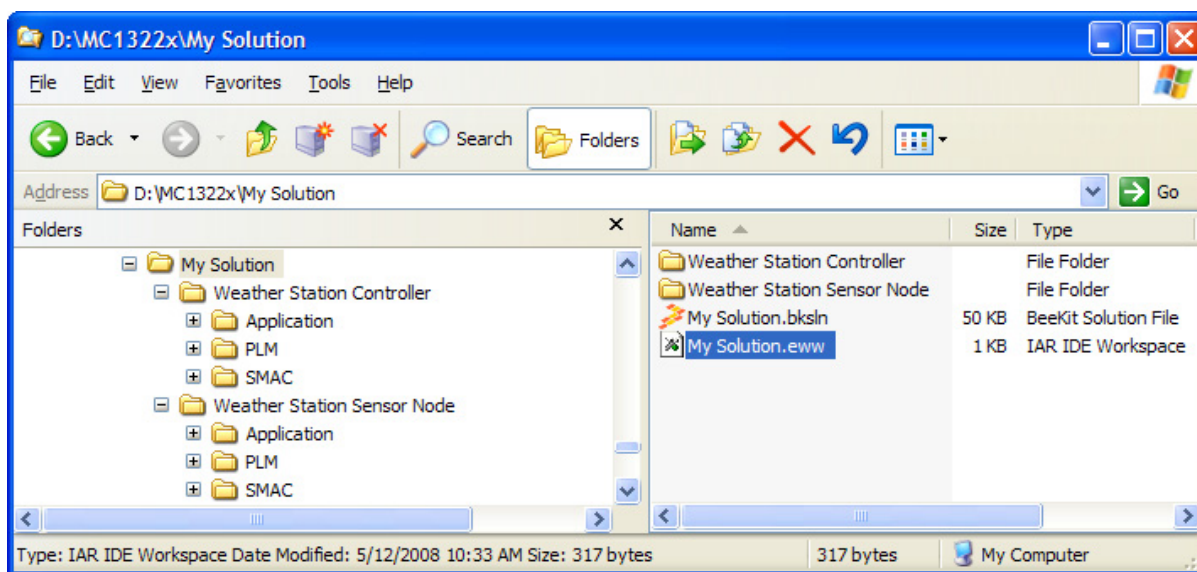


**Figure 9-1. BeeKit Created, Wireless UART Directory Structure**

For further details about how to use BeeKit, see the *BeeKit Wireless Connectivity Toolkit User's Guide* (BKWCTKUG).

## 9.2 Open, Compile, and Load the Weather Station

1. Using the IAR Embedded Workbench, open the [My Solution] work space (`MySolution.eww`) as shown in Figure 9-2.



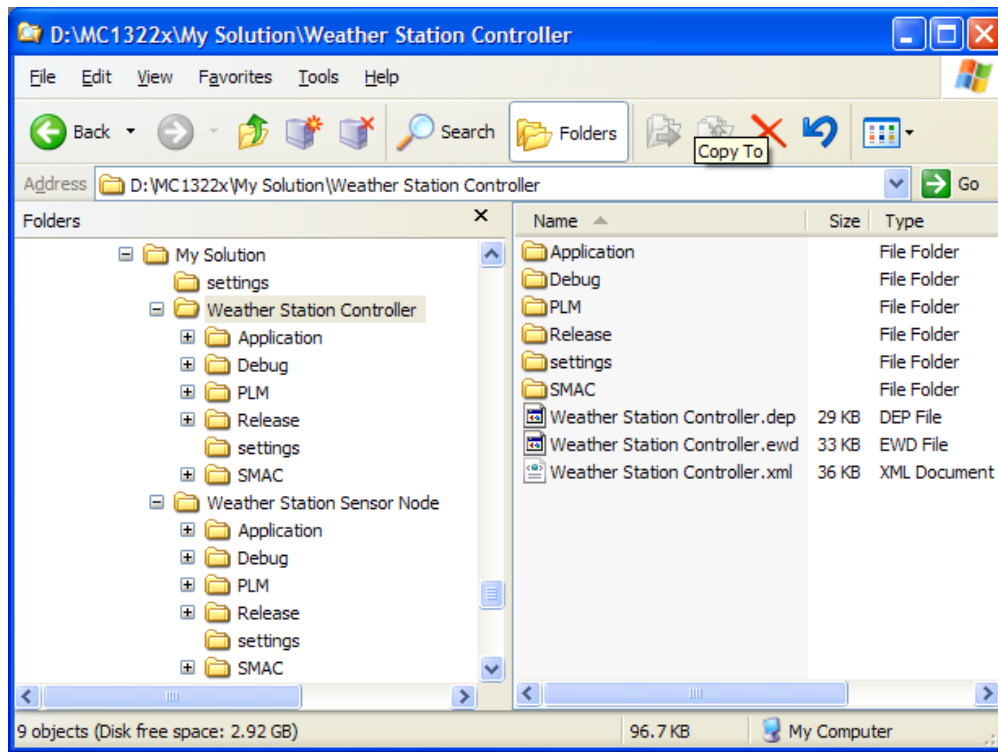
**Figure 9-2. Opening Weather Station Work Space**

2. Select “Release” in the Workspace window.
3. With the “Weather Station Controller“ highlighted, click on Project -> Rebuild All.

The folders Release, Debug, and the settings are now created in the project structure as shown in Figure 9-3.

4. With the “Weather Station Sensor Node” highlighted, click on Project -> Rebuild All.

The folders Release, Debug, and the settings are now created in the project structure similar to what is shown in [Figure 9-3](#).



**Figure 9-3. Release, Debug, and Settings**

The `Weather Station Controller.bin` file is placed at the following directory location:

```
[My Solution Directory]\Weather Station Controller\Release\Exe\
```

The `Weather Station Sensor Node.bin` file is placed at the following directory location:

```
[My Solution Directory]\Weather Station Sensor Node\Release\Exe\
```

5. Load the `Weather Station Controller.bin` and `Weather Station Sensor Node.bin` files to the boards using the JTAG connection. To download the image, connect the J-Link ARM debugger and press [Ctrl]+D or just click the Debug button at the IAR Embedded Workbench IDE.
6. At this point the weather station is running without the PC Application. After showing the Freescale logo, the “Wind Speed” screen appears on the Network Node LCD display as shown in [Figure 9-4](#).





Figure 9-4. Network Node Board LCD Display

7. Use the Network Node joystick or switches to change the parameters as follows:

Figure 9-5. Joystick or Switch Parameters

Joystick Position	Switch	NCB	SRB
Joystick Right	SW1	Metric/Standard System Selection	Set calibration
Joystick Down	SW2	Switch Screen. Change which sensor to watch.	Not Used
Joystick Left	SW3	Backlight On/Off	Not Used
Joystick Up	SW4	Change Channel	Change Channel

### 9.3 Weather Station PC Application

The Freescale Weather Station PC application allows users to monitor simulated weather behavior using a PC GUI application through the MC1322x SMAC network. This system setup uses two boards:

- One board is connected to the PC through the serial interface to communicate with the GUI. This board is a MC1322x Network Node running the embedded SMAC application and is used only as a receiver.
- The other board must be a MC1322x Sensor Node that transmits the information that it senses to the Network Node receiver. The Sensor Node can monitor temperature, wind direction, wind speed, air pressure, and battery voltage.

#### 9.3.1 Features

The Freescale Weather Station PC application has the following features:

- An easy-to-use graphical user interface
- Real time visualization of the data frames of the devices in the network
- Save log files with the weather information
- Run in real time or from a previously saved file
- Switch between different units of measure (metric or American/British)
- Shows the maximum and minimum values obtained from each sensor during the demonstration
- Shows the history of the weather behavior using bar graphics

Figure 9-6 shows the Network Node (SMAC Coordinator) connected to the PC and the Sensor Node (SMAC Sensor) communicating with the Coordinator. As shown in this figure, the icons on the PC screen represent the values as sensed by the Sensor Node.

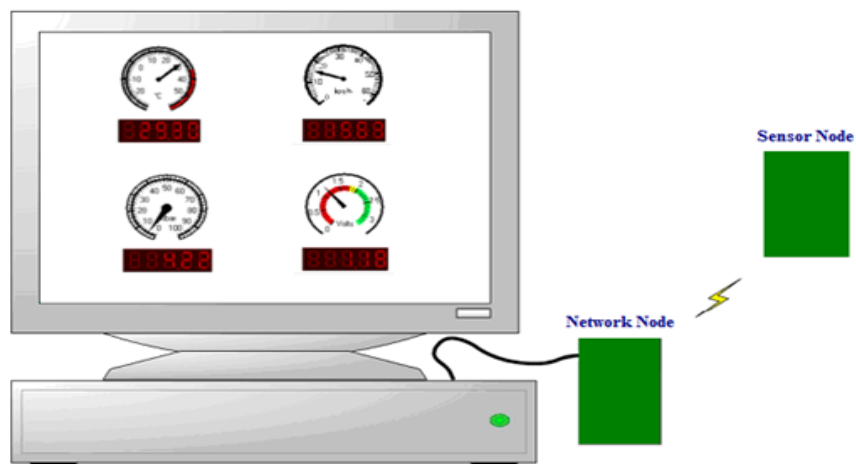


Figure 9-6. Weather Station System Setup

## 9.3.2 Connecting to a Network Node

To run the Weather Station PC application, perform the following tasks:

1. Launch the `Weather Station.exe`. Click on Start -> Programs->Freescale BeeKit -> Weather Station -> Weather Station.

The Weather Station main window appears as shown in Figure 9-7.

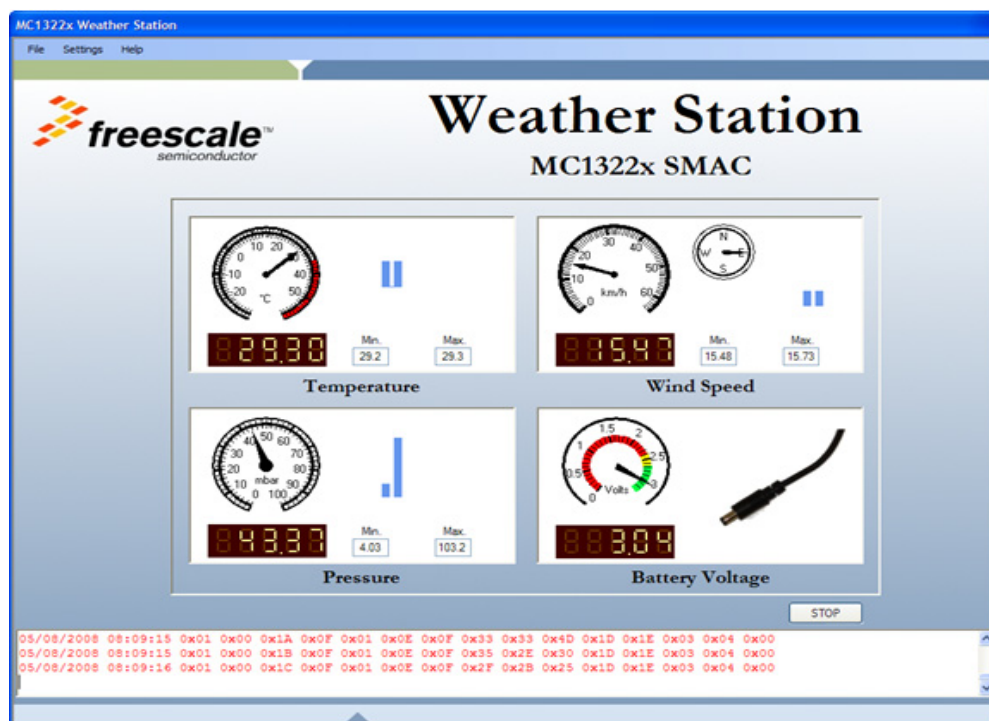
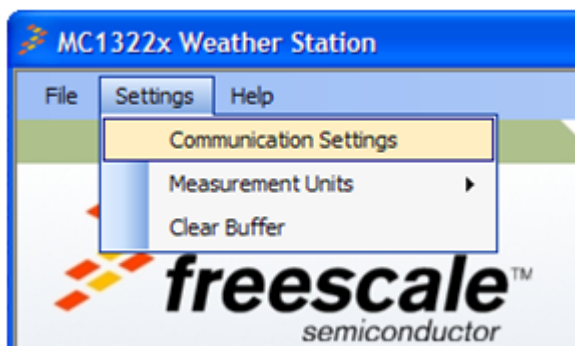


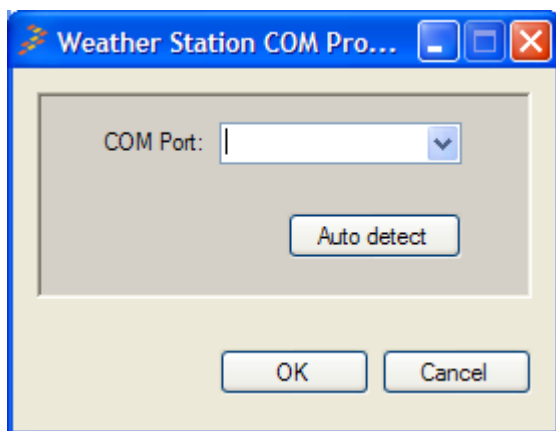
Figure 9-7. Weather Station Main Window

2. Click on Settings -> Communication Settings as shown in [Figure 9-8](#).



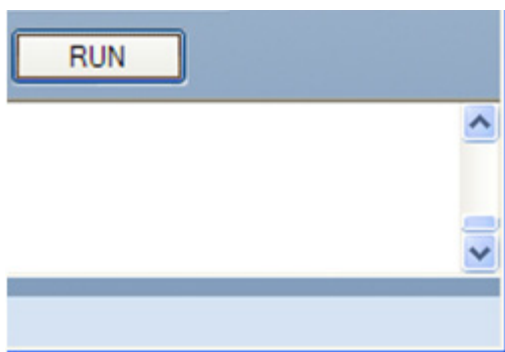
**Figure 9-8. Communication Settings Menu**

3. Press the autodetect button to find MC1322x boards connected or choose the appropriate COM port where the Network Node is connected as shown in [Figure 9-9](#).



**Figure 9-9. Communication Options Selection**

4. Click on the RUN button as shown in [Figure 9-10](#).



**Figure 9-10. RUN/STOP Button**

### 9.3.3 Data Packet Structure

The Weather Station PC application displays various weather related levels and values and also displays the received frames at the bottom of the main window. As shown in [Figure 9-7](#), the bottom of the main window shows the data packet sent by the Sensor Node to the Network Node. The data packet is divided into fifteen bytes of information with a header and a tail. However, the tail (the last byte) is not displayed. [Figure 9-11](#) shows the data structure details.

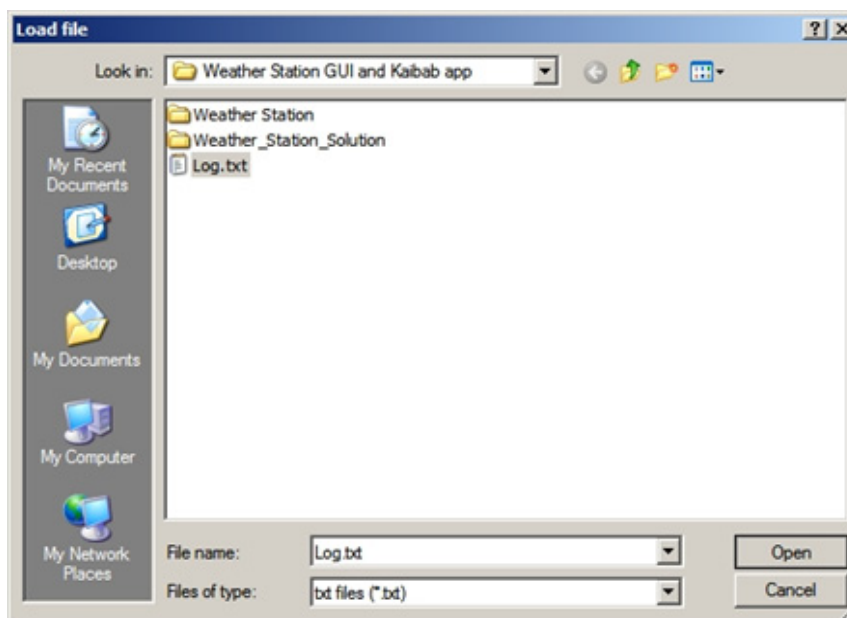
		Network Node Data (2 bytes)		Sensor Node Data (11 bytes)					
	Bytes 1-2	Bytes 3-4	Bytes 5-6	Bytes 7-8	Bytes 9-10	Bytes 11-12	Bytes 13-14	Byte 15	
Date/Time	Network Device Info	Sequence Number Operating Channel	Wind Direction (0-360°)	Wind Speed (n.n)	Air Pressure (n.n)	Temperature	Battery Voltage (n.n)	Battery Yes/No	

**Figure 9-11. Weather Station Data Frame Structure**

### 9.3.4 Loading a Pre-existing Log File

This section describes how to load and run a pre-existing log file. To load and run a pre-existing log file, perform the following tasks:

1. Launch the Weather Station PC application. The Weather Station main window appears as shown in [Figure 9-7](#).
2. Click on File -> Load. The Load file window appears as shown in [Figure 9-12](#).
3. Navigate to the Weather Station folder and highlight the `Log.txt` file.
4. Click the Open button.



**Figure 9-12. Load File Window**

5. From the Weather Station main window, click the RUN button.
6. The application starts as shown in Figure 9-13.

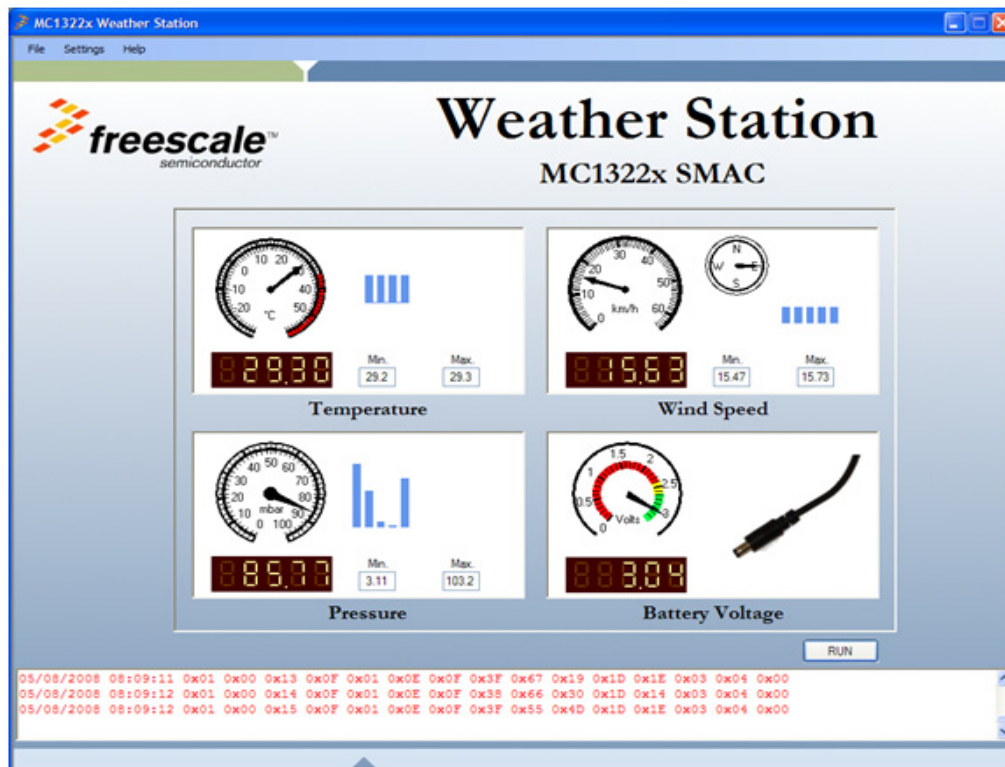


Figure 9-13. Weather Station Running from a Log File

7. Click the Stop button to halt the application.
8. Click the Run button to start the application again.

While the Weather Station PC application is running, users can change the measurement units and clear the buffer.

### NOTE

It is not possible to change the Log, Load, or Communication Settings configuration of the Weather Station PC application while it is running.

9. To change measurement units, click on Settings -> Measurement Units.
10. To clear the buffer, click on Settings -> Clear Buffer.

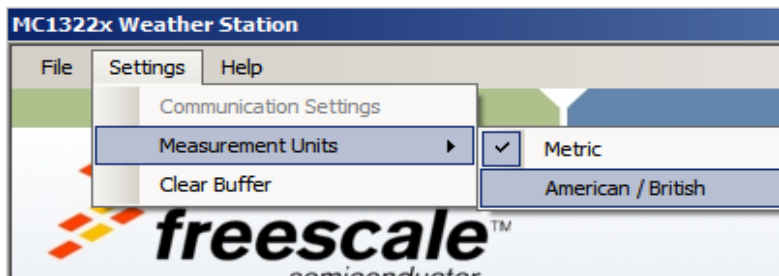


Figure 9-14. Changing Measurement Units or Clearing Buffer



## Chapter 10

# Over The Air Programmer Demonstration

The Over the Air Programmer (OTAP) application allows users to update a board's FLASH remotely without a physical connection. Given an OTAP enabled application and an OTAP programmer, users can replace an existing application on a board with a new application. Two boards are required for the OTAP application:

- One board used as the OTAP Programmer
- One board used as the OTAP-enabled target

Freescale recommends that both of the images to be flashed are OTAP-enabled applications.

The following summarizes what users will accomplish with the OTAP application:

- On the OTAP Programmer Board:
  - Download and run the OTAP Programmer software
  - Download an OTAP-enabled application via the UART. This example uses the Wireless UART.
    - The Wireless UART application must have its OTAP module property enabled when the project is generated in BeeKit
  - Any of the MC1322x development boards can be used as the OTAP Programmer
- OTAP-enabled target Board (The board having its firmware updated.)
  - Download and run an OTAP-enabled application on the board. This example uses the Accelerometer Demonstration application. The Accelerometer Demonstration application will be replaced by the Wireless UART application using the OTAP Programmer.
    - The Accelerometer Demonstration application must have its OTAP module property enabled when the project is generated in BeeKit.
  - Any of the MC1322x development boards can be used as an OTAP enabled target board.

If the following conditions are not met, the OTAP programmer will not function properly:

- The OTAP enabled target board application must be in the receive mode most of the time
- The devices on the network must have different IDs

See [Section 1.3, “UART/USB Virtual COM Port Setup”](#) for information about how to set up a virtual COM port for this application.

## 10.1 Generating a Project From BeeKit

Once the UART/USB virtual ports have been configured, generate the project from BeeKit as follows:

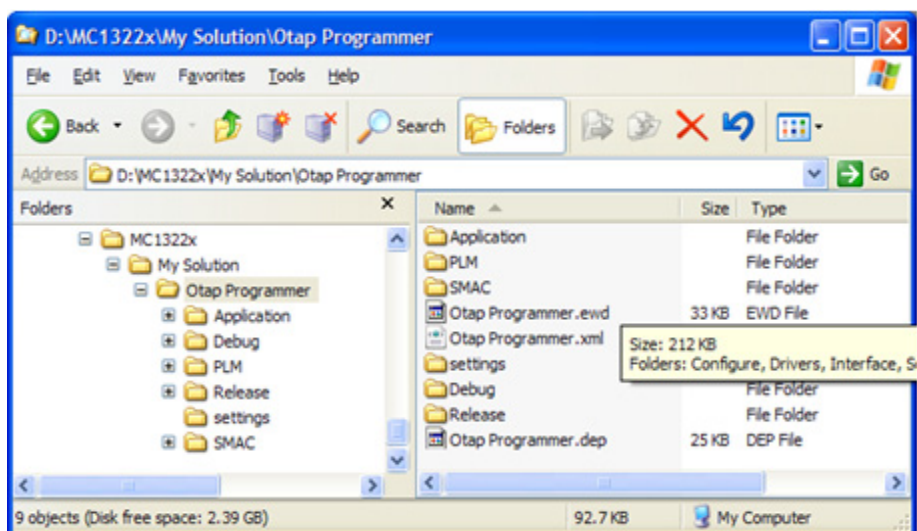
1. Open BeeKit (Start->Programs->Freescale BeeKit->Freescale BeeKit).
2. On BeeKit select the MC1322x SMAC codebase (File menu -> Select Codebase...)
3. Click on File -> New Project and choose the OTAP Programmer template.
4. Follow the steps as displayed in the New Project wizard.
5. Configure the properties as needed.
6. Validate the solution.
7. Export the solution.

For further details on how to use BeeKit, see the *BeeKit Wireless Connectivity Toolkit User's Guide* (BKWCTKUG).

## 10.2 Open, Compile, and Load the OTAP Programmer

1. Using the IAR Embedded Workbench, open the OTAP work space (`My Solution.eww`).
2. Select "Release" in the Workspace window.
3. Click on Project -> Rebuild All.

The folders Release, Debug, and the settings are now created in the project structure as shown in [Figure 10-1](#).



**Figure 10-1. Release, Debug, and Settings**

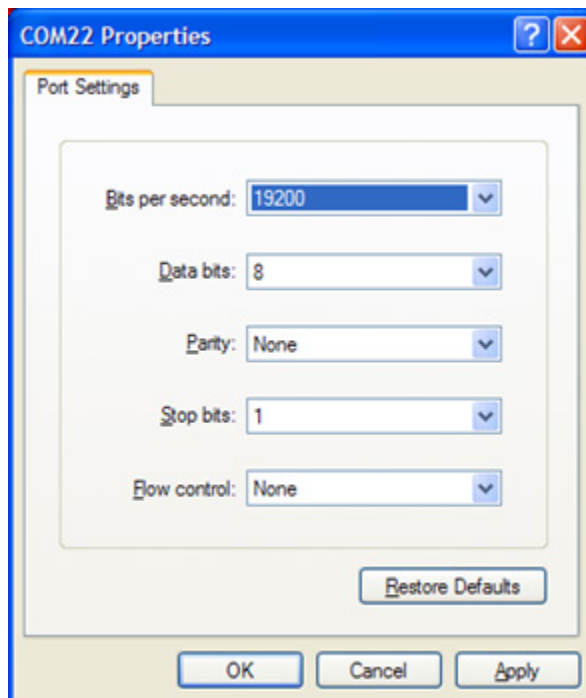
4. The `OTAPProgrammer.bin` file is placed at the following directory location:

```
[Project Directory]\Release\Exe\
```

5. Load the `OTAPProgrammer.bin` file to the desired board. Connect the JTAG interface and click on the IAR Embedded Workbench IDE Debug button.

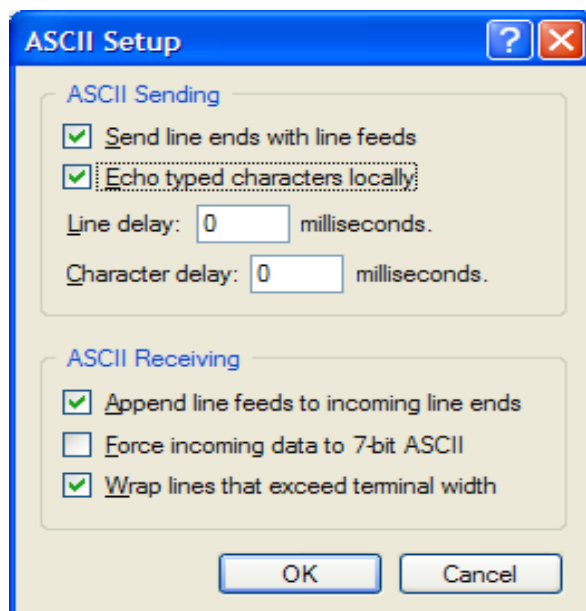


6. Use a PC terminal communications program, such as Hyper Terminal, and set the correct baud rate, data bits, parity, COM port, and flow control. [Figure 10-2](#) shows the default MC1322x SMAC RS232 settings.



**Figure 10-2. Default OTAP RS-232 Settings**

7. In the PC terminal program, set the properties in the optional settings as shown in [Figure 10-3](#).



**Figure 10-3. Additional Terminal Program Settings**

## 10.3 Downloading an OTAP-enabled Image to the OTAP Programmer Board

The OTAP Programmer Board does not have a `.srec` file (image) flashed on it by default. Users must first download a valid image to the OTAP Programmer Board using the serial terminal. To download the image, complete the following steps:

1. Turn on the OTAP Programmer Board (1322x-Network Node).
2. Press SW2 on the 1322x-Network Node to enter the COM mode.
3. Once the board is in COM mode, the serial terminal displays the information as shown in Figure 10-4.

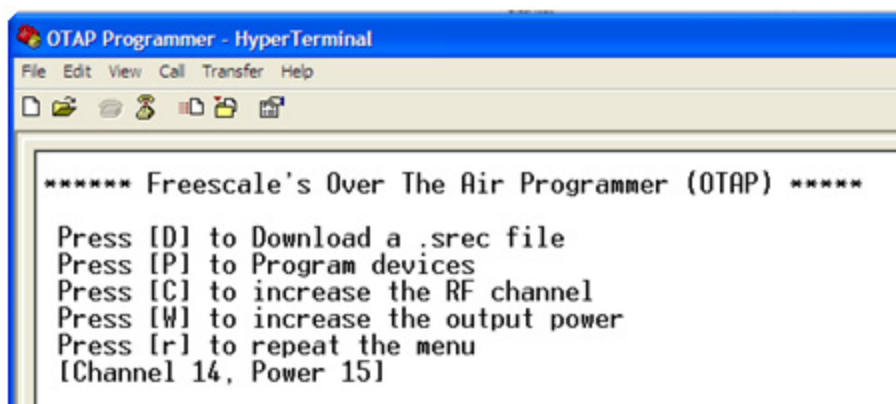


Figure 10-4. OTAP Start Message

4. Press D to download a `.srec` file, then click on Transfer -> Send Text File as shown in Figure 10-5.

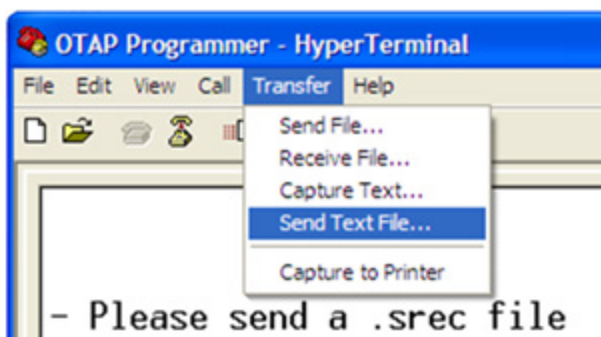
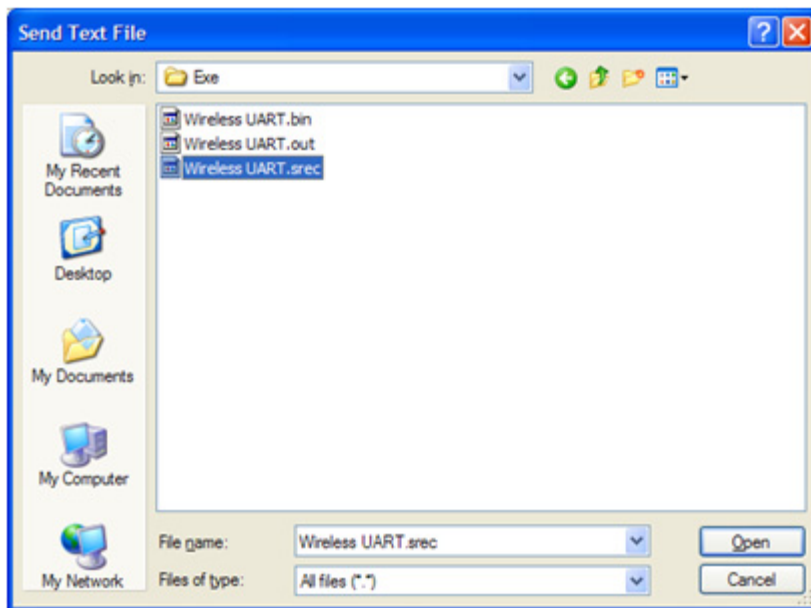


Figure 10-5. Send a Text (.srec) File to the OTAP Programmer

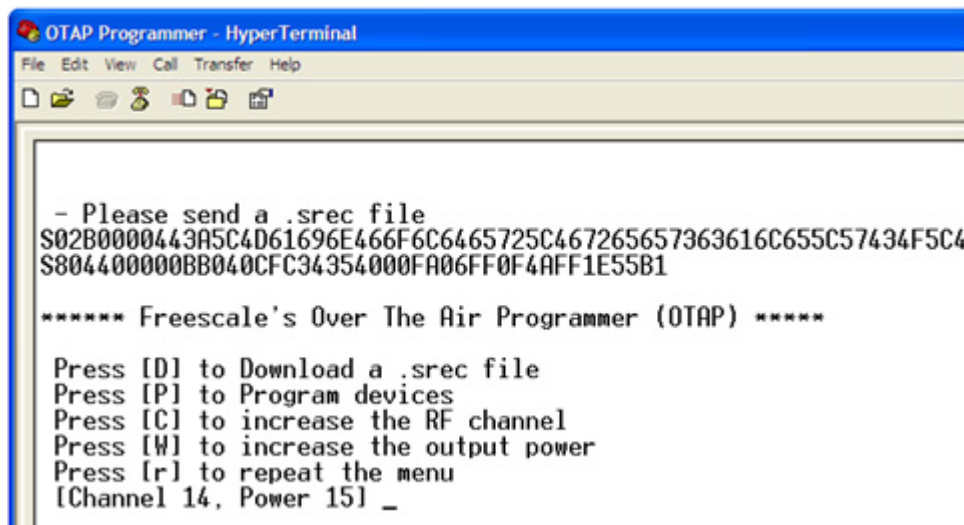
5. To select and send a .srec file as a text file using the serial terminal, click on Transfer -> Send File and the Send Text File window appears as shown in Figure 10-6. Select the appropriate .srec file, then click on the Open button.



**Figure 10-6. Downloading the Image to the OTAP Programmer**

Ensure that the application being loaded is an OTAP Enabled application. This example uses the Wireless UART.

When the file transfer is complete, the serial terminal displays the main menu again as shown in Figure 10-7.



**Figure 10-7. Transferring the Image to the OTAP Programmer**

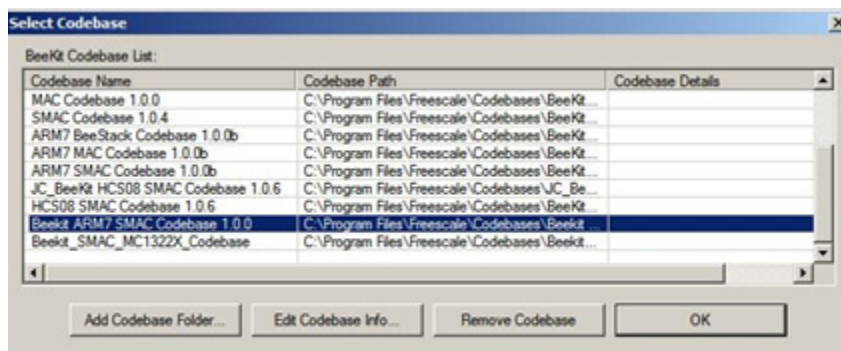
At this point the OTA Programmer has stored a new application that can be used to reprogram any application with the OTAP option enabled. To program the new application to a board with OTAP enabled, see [Section 10.5, “Transmitting the New Image to the OTAP-enabled Board”](#).

## 10.4 Downloading an OTAP-enabled Application

The example in this section uses the Accelerometer demonstration to show how to enable the OTAP option in a device.

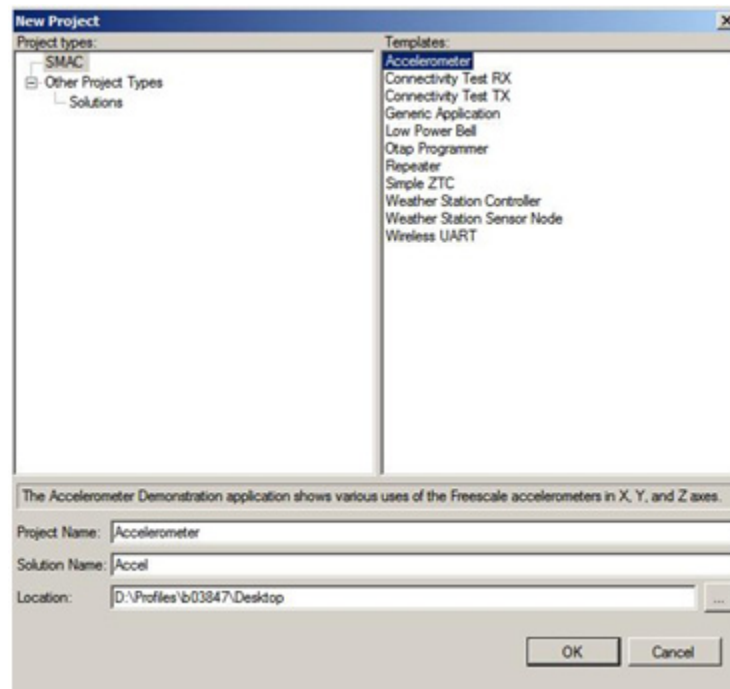
To make a new Beekit application with the OTAP option enabled, perform the following tasks:

1. Launch Beekit and click on File -> Select Codebase and choose the "Beekit ARM7 SMAC Codebase 1.0.0" codebase as shown in [Figure 10-8](#).



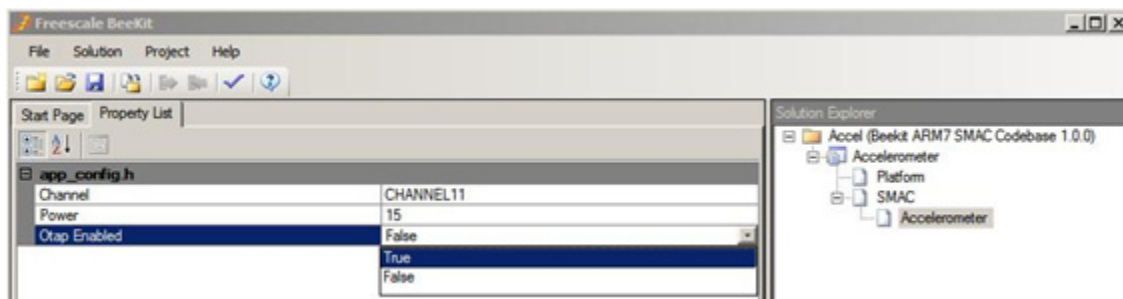
**Figure 10-8. Select SMAC Codebase**

2. Click on File -> New Project.
3. Select the Accelerometer application and choose a name for the solution. In this case the solution name chosen was Accel as shown in [Figure 10-9](#).



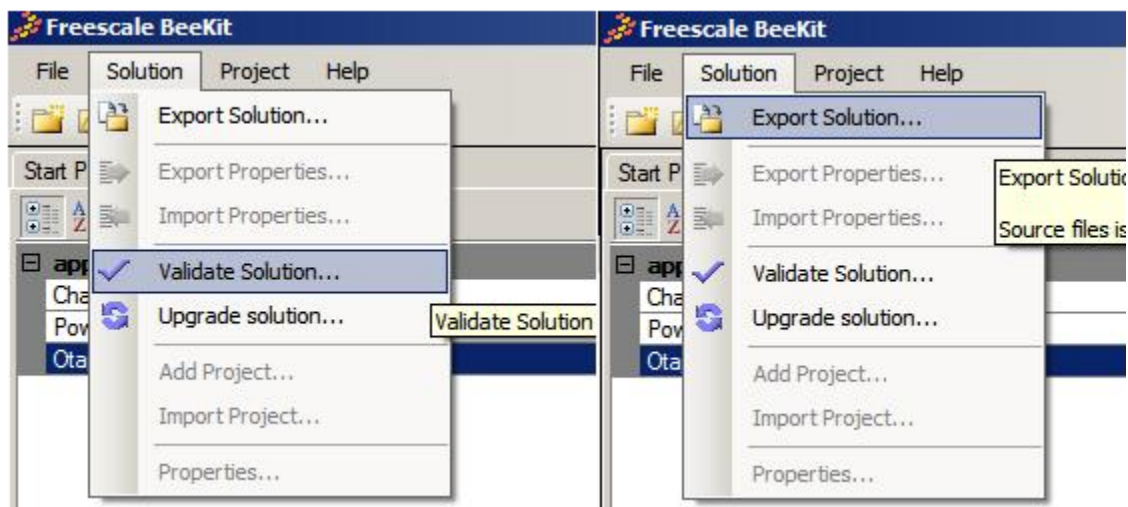
**Figure 10-9. Select Accelerometer Application**

4. Select a hardware target board for the project and click on the finish button. Users can select any available target board.
5. From the BeeKit main window (solution explorer area) select the Accelerometer and change the OTAP Enabled attribute from False to True as shown in [Figure 10-10](#).



**Figure 10-10. Set OTAP Enabled to TRUE**

6. Validate the solution as shown in [Figure 10-11](#).
7. Export the solution as shown in [Figure 10-11](#).



**Figure 10-11. Validate and Export Solution**

The application is ready to open in IAR Embedded Workbench and ready for download to the chosen board. Download the Accelerometer image by following the procedure in [Section 1.1, “Loading Applications Into a Board Using the JTAG J-Link ARM Debugger”](#).

Once the application is running on the board, users can re-program the board over the air using the OTAP Programmer Board.

## 10.5 Transmitting the New Image to the OTAP-enabled Board

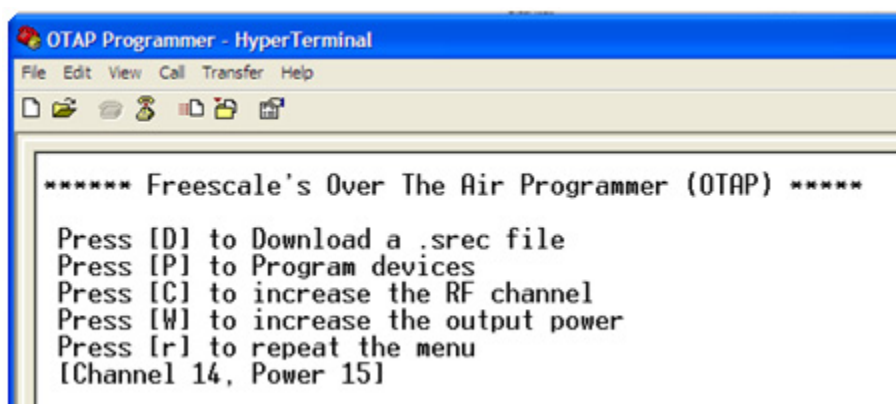
Users must have an OTAP Programmer board running with a valid .srec file image and a device with an OTAP-enabled application running. This example uses the Accelerometer Demonstration application.

There are two options for users to FLASH the device over the air:

- Serial Interface ([Section 10.5.1, “Using the Serial Interface”](#))
- LCD Interface ([Section 10.5.2, “Using The LCD Interface”](#))

### 10.5.1 Using the Serial Interface

1. Press the Reset button on the OTAP Programmer Board.
2. Press SW2 on the OTAP Programmer Board. The serial terminal displays text as shown in [Figure 10-12](#).



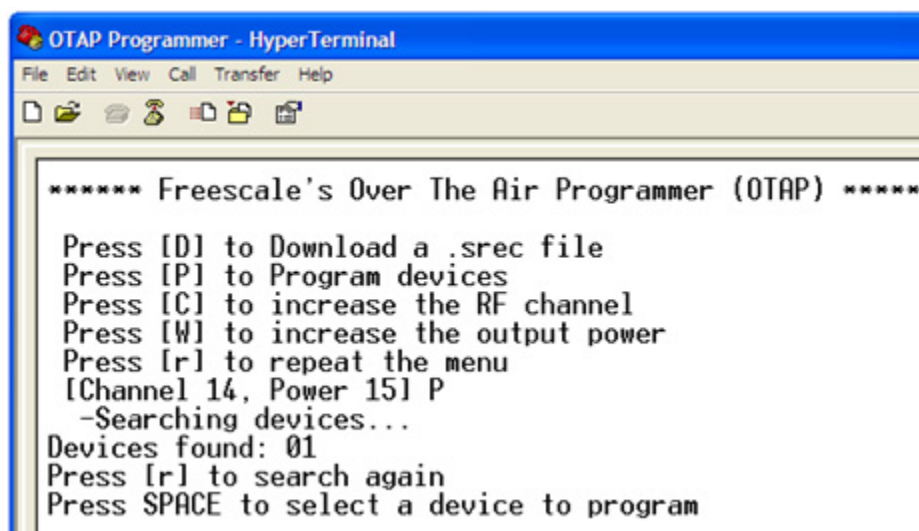
```
OTAP Programmer - HyperTerminal
File Edit View Call Transfer Help

***** Freescale's Over The Air Programmer (OTAP) *****

Press [D] to Download a .srec file
Press [P] to Program devices
Press [C] to increase the RF channel
Press [W] to increase the output power
Press [r] to repeat the menu
[Channel 14, Power 15]
```

Figure 10-12. OTAP Programmer Start Message

3. Press "P" on the keyboard to search for devices to program. The serial terminal appears as shown in [Figure 10-13](#).



```
OTAP Programmer - HyperTerminal
File Edit View Call Transfer Help

***** Freescale's Over The Air Programmer (OTAP) *****

Press [D] to Download a .srec file
Press [P] to Program devices
Press [C] to increase the RF channel
Press [W] to increase the output power
Press [r] to repeat the menu
[Channel 14, Power 15] P
-Searching devices...
Devices found: 01
Press [r] to search again
Press SPACE to select a device to program
```

Figure 10-13. OTAP Programmer Found a Device



4. Once the OTAP Programmer Board found a device, press the SPACE Bar on the keyboard. The OTAP Programmer shows the device address (ID) in the serial terminal as shown in [Figure 10-14](#). In this case the device address is 0x02. If more OTAP-Enabled devices were found, press the SPACE Bar on the keyboard to see the device IDs.

```

OTAP Programmer - HyperTerminal
File Edit View Call Transfer Help

***** Freescale's Over The Air Programmer (OTAP) *****

Press [D] to Download a .srec file
Press [P] to Program devices
Press [C] to increase the RF channel
Press [W] to increase the output power
Press [r] to repeat the menu
[Channel 14, Power 15] P
-Searching devices...
Devices found: 01
Press [r] to search again
Press SPACE to select a device to program
02 Press [L] to program this device or [r] to see the COM menu again

```

**Figure 10-14. OTAP Programmer Shows Device's ID**

5. Press "L" on the keyboard and the OTAP Programmer flashes the device over the air. Users must wait for the Program Success message to appear in the serial terminal window and not press any buttons on the OTAP Programmer Board or on the device being flashed. The Program Success message is shown in [Figure 10-15](#).

```

OTAP Programmer - HyperTerminal
File Edit View Call Transfer Help

***** Freescale's Over The Air Programmer (OTAP) *****

Press [D] to Download a .srec file
Press [P] to Program devices
Press [C] to increase the RF channel
Press [W] to increase the output power
Press [r] to repeat the menu
[Channel 14, Power 15] P
-Searching devices...
Devices found: 01
Press [r] to search again
Press SPACE to select a device to program
02 Press [L] to program this device or [r] to see the COM menu again
L
***** Freescale's Over The Air Programmer (OTAP)*****

- PROGRAMMING...

-Please wait.
- Program success !!
- Press [r] to search again

```

**Figure 10-15. Device Programming Success**



## 10.5.2 Using The LCD Interface

1. Press the Reset button on the OTAP Programmer Board. The main screen appears as shown in Figure 10-16.

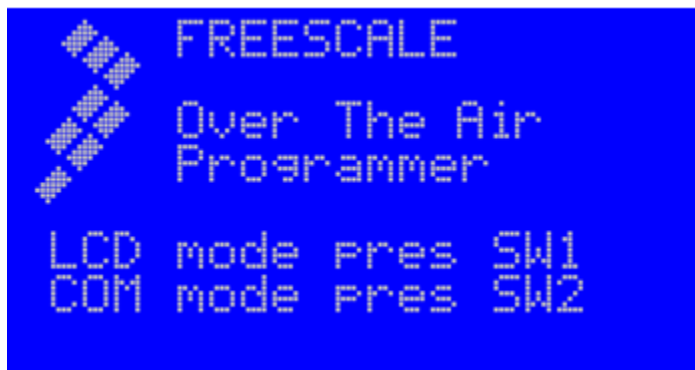


Figure 10-16. OTAP Programmer Main LCD Screen

2. Press SW1 on the OTAP Programmer Board. The OTAP menu appears as shown in Figure 10-17.

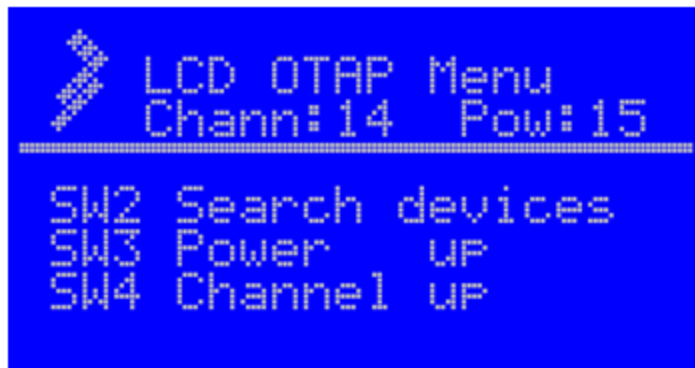


Figure 10-17. LCD OTAP Menu

3. Press SW2 to search for devices to program. The searching devices screen appears as shown in Figure 10-18.

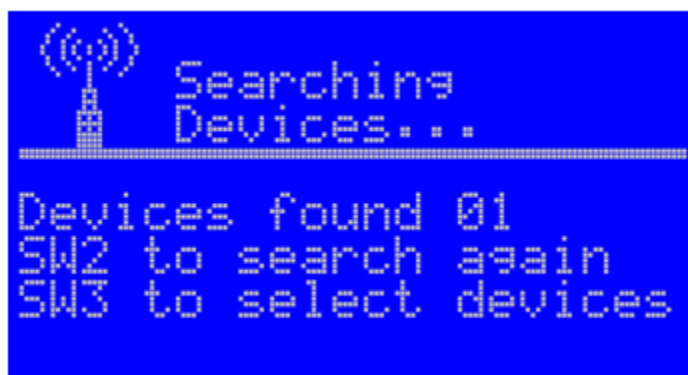
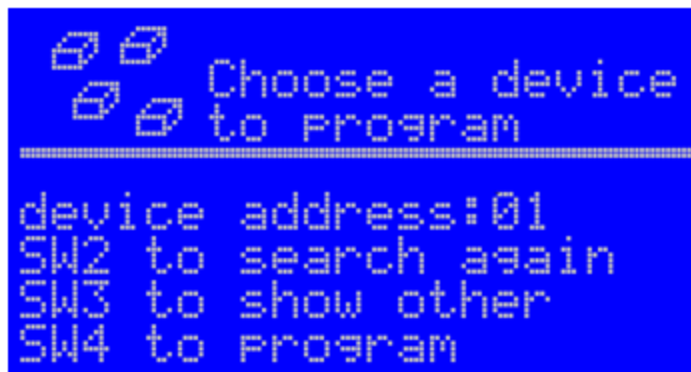


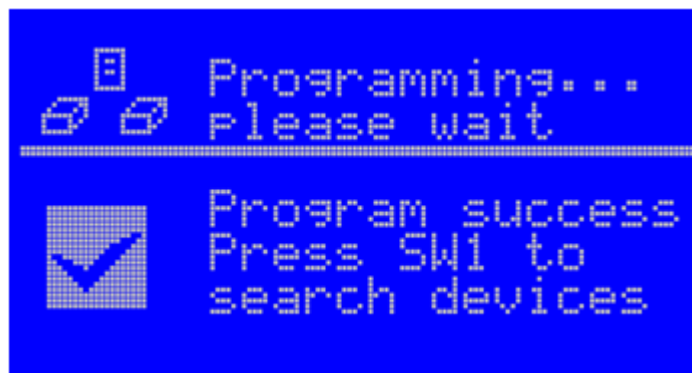
Figure 10-18. LCD OTAP Search for Devices

4. Once the OTAP Programmer Board finds a device, press SW3. The OTAP Programmer shows the device address (ID) on the screen. In this case, the device address is 0x01 as shown in [Figure 10-19](#). If more OTAP-Enabled devices were found, press SW3 to see the device IDs.



**Figure 10-19. LCD OTAP Devices Screen**

5. Press SW4 and the OTAP Programmer flashes the device over the air. Users must wait for the Program Success message to appear in the serial terminal window and must not press any buttons on the OTAP Programmer Board or on the device being flashed. The Program Success message is shown in [Figure 10-20](#).



**Figure 10-20. LCD OTAP Program Success Screen**

## 10.6 Verifying the Transmitted Image

To verify that the image transmitted by the OTAP Programmer is correct, search for the device using the OTAP programmer board. If the OTAP Programmer finds the board again, then the application was correctly flashed.

In this example, the original application loaded on the target board was the Accelerometer Demonstration. The new application flashed to the target board by the OTAP Programmer was the Wireless UART Demonstration. After reprogramming, Wireless UART operation can be verified as described in [Chapter 2](#), “Wireless UART Demonstration”.